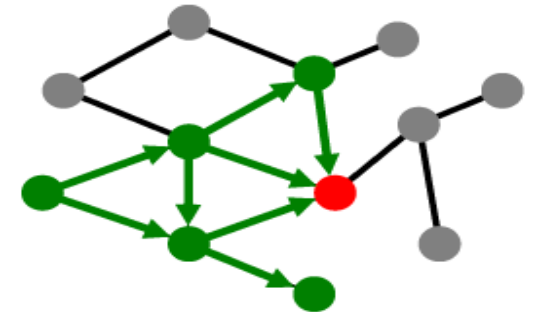


How to model diffusion?

■ Probabilistic models:

- Models of influence or disease spreading
 - An infected node tries to “push” the contagion to an uninfected node
- **Example:**
 - You “catch” a disease with some prob. from each active neighbor in the network



■ Decision based models:

- Models of product adoption, decision making
 - A node observes decisions of its neighbors and makes its own decision
- **Example:**
 - You join demonstrations if k of your friends do so too

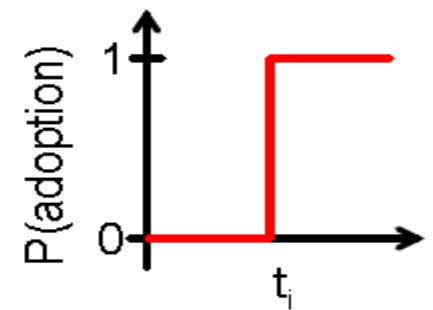
Decision-based diffusion models

Collective action
[Granovetter 1978]

- **Collective Action** [Granovetter, '78]
 - Model where everyone sees everyone else's behavior
 - **Examples:**
 - Clapping or getting up and leaving in a theater
 - Keeping your money or not in a stock market
 - Neighborhoods in cities changing ethnic composition
 - Riots, protests, strikes

The model of collective action

- **n people – everyone observes all actions**
- Each person i has a threshold t_i
 - Node i will adopt the behavior iff at least t_i other people are adopters:
 - **Small t_i : early adopter**
 - **Large t_i : late adopter**
- **The population is described by $\{t_1, \dots, t_n\}$**
 - **$F(x)$** ... fraction of people with threshold $t_i \leq x$



Dynamics of collective action

- Think of the step-by-step change in number of people adopting the behavior:

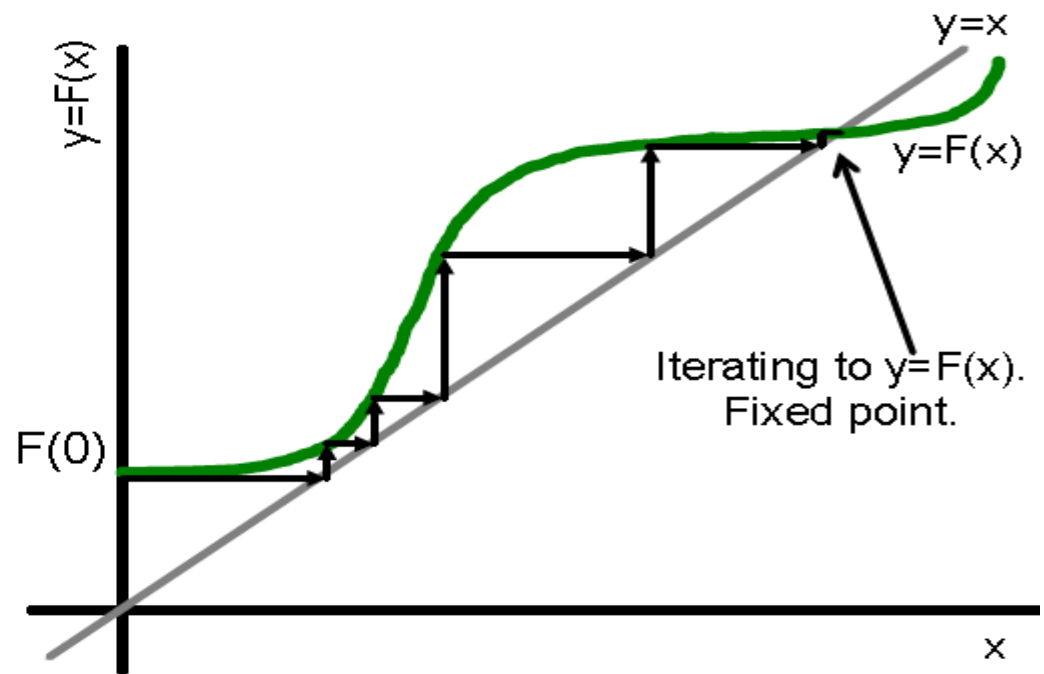
- $F(x)$... fraction of people with threshold $\leq x$
- $s(t)$... number of participants at time t

- Easy to simulate:

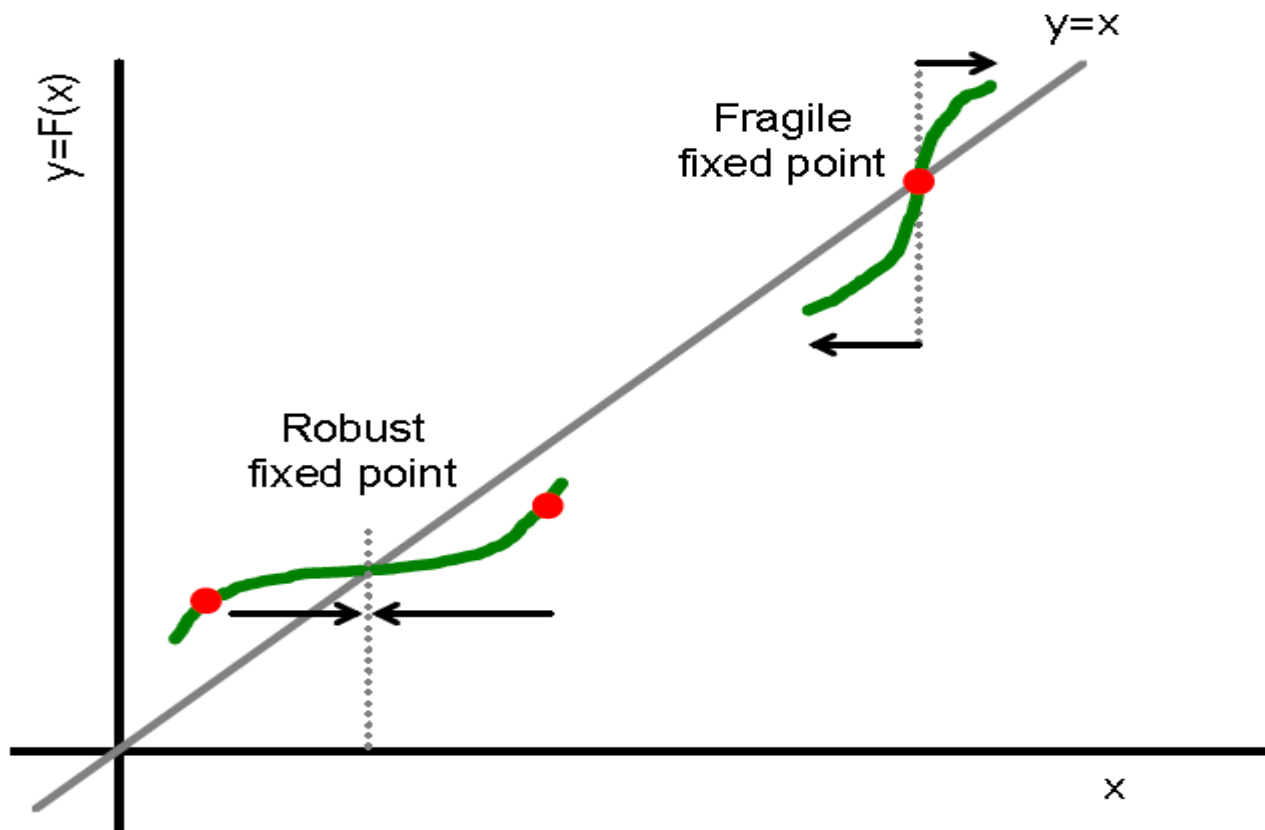
- $s(0) = 0$
- $s(1) = F(0)$
- $s(2) = F(s(1)) = F(F(0))$
- $s(t+1) = F(s(t)) = F^{t+1}(0)$

- Fixed point: $F(x)=x$

- There could be other fixed points but starting from 0 we never reach them



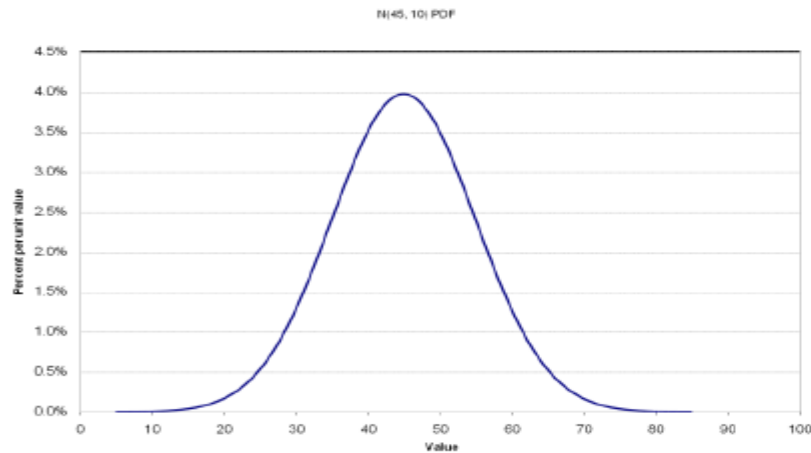
Fragile vs. robust fixed points



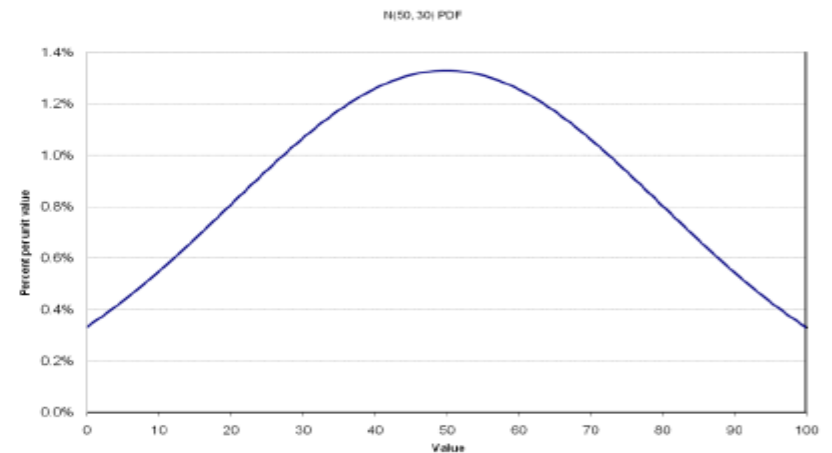
Distribution of thresholds (trust)

- Each threshold t_i is drawn independently from some distribution $F(x) = Pr[thresh \leq x]$
 - **Suppose:** Normal with $\mu=n/2$, variance σ

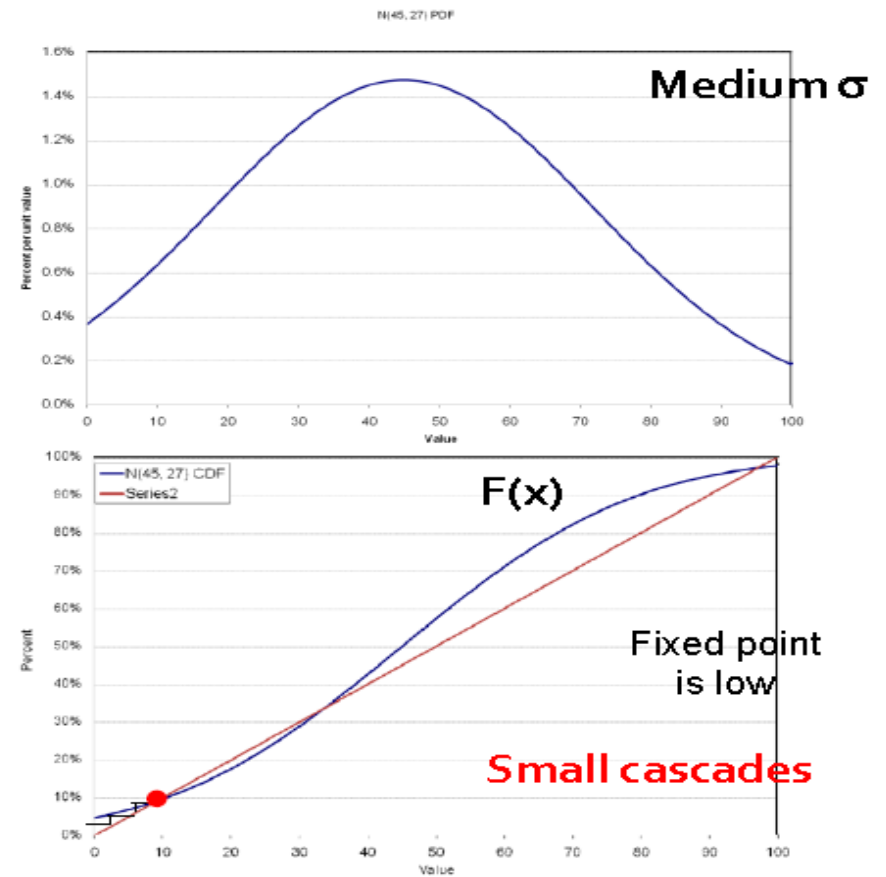
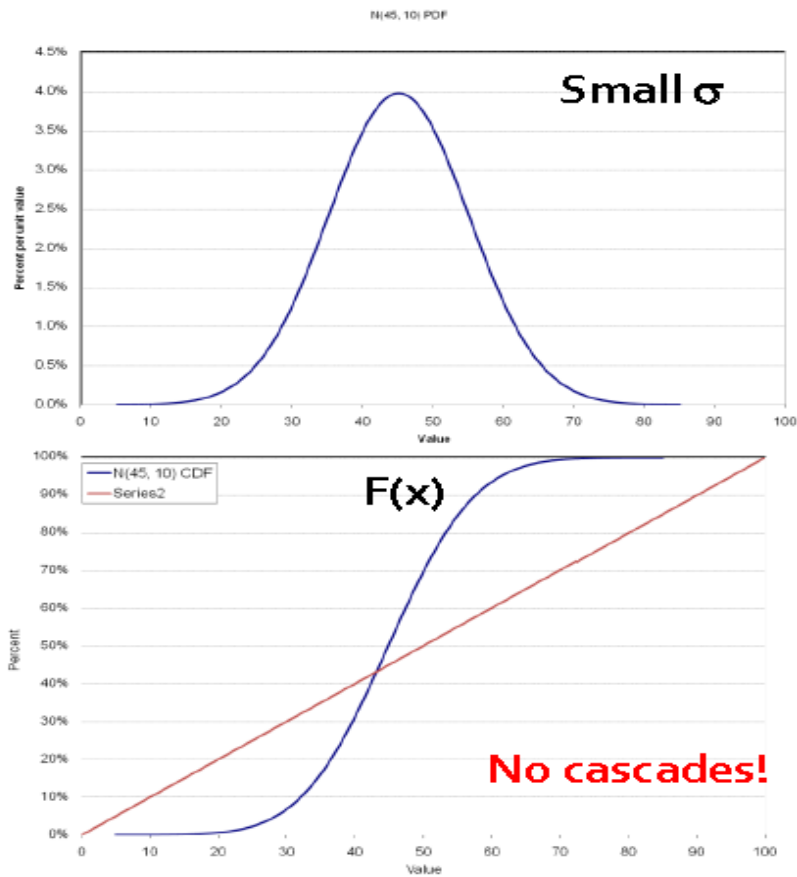
Small σ :



Large σ :

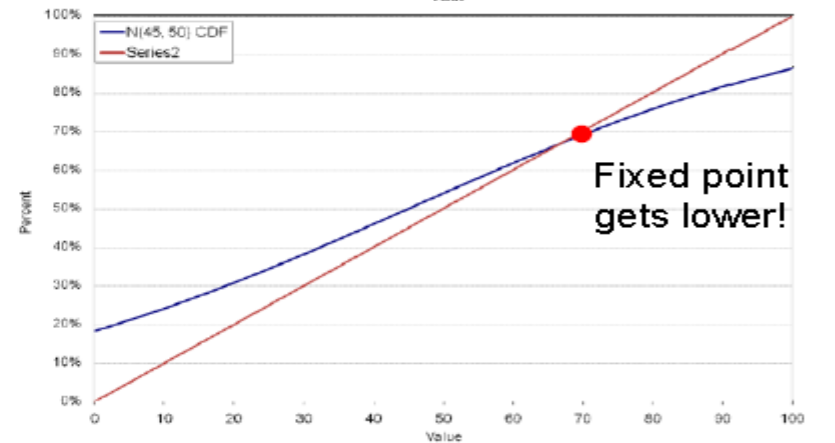
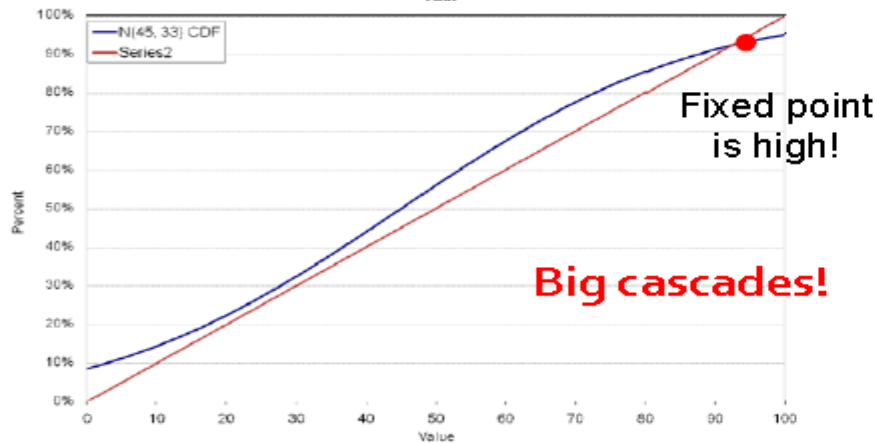
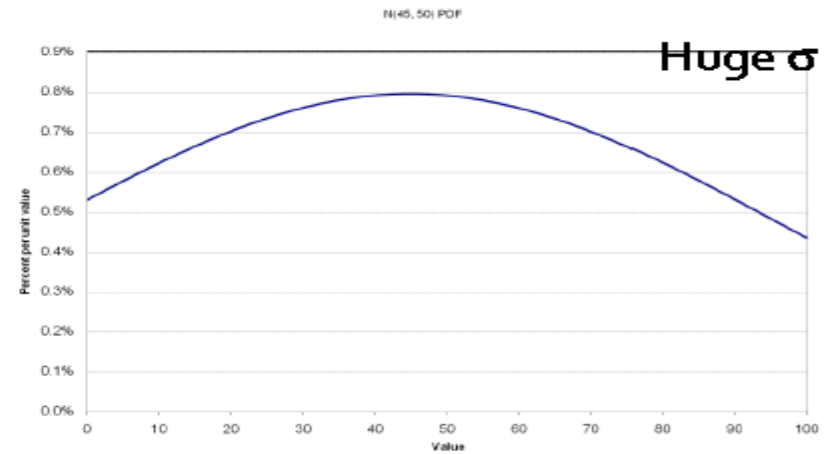
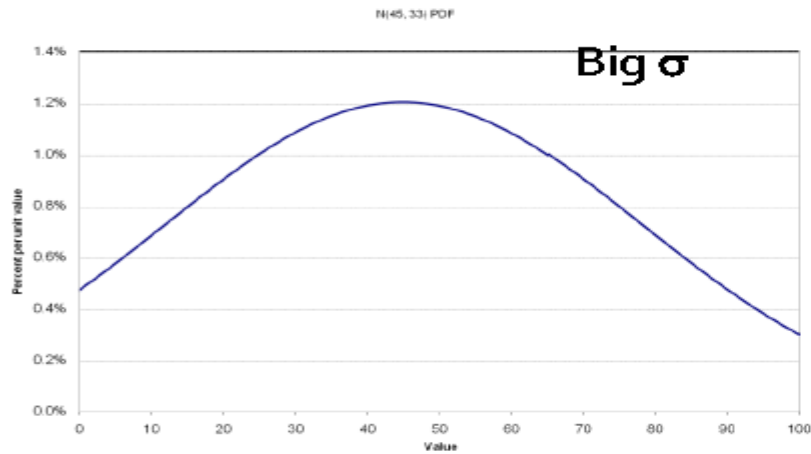


Simulation

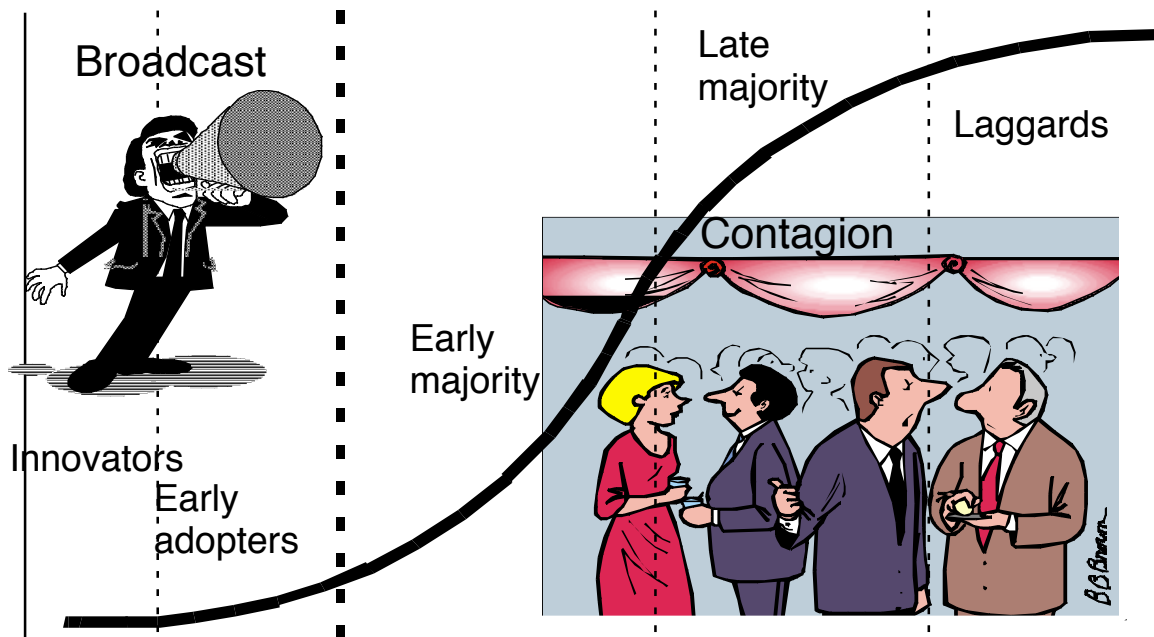


Bigger variance let's you build a bridge from early adopters to mainstream

Simulation



But if we increase the variance even more we move the higher fixed point lower



Weaknesses of the CA model

- **It does not take into account:**
 - No notion of social network – more influential users
 - It matters who the early adopters are, not just how many
 - Models people's awareness of size of participation not just actual number of people participating
 - **Modeling thresholds**
 - Richer distributions
 - Deriving thresholds from more basic assumptions
 - game theoretic models

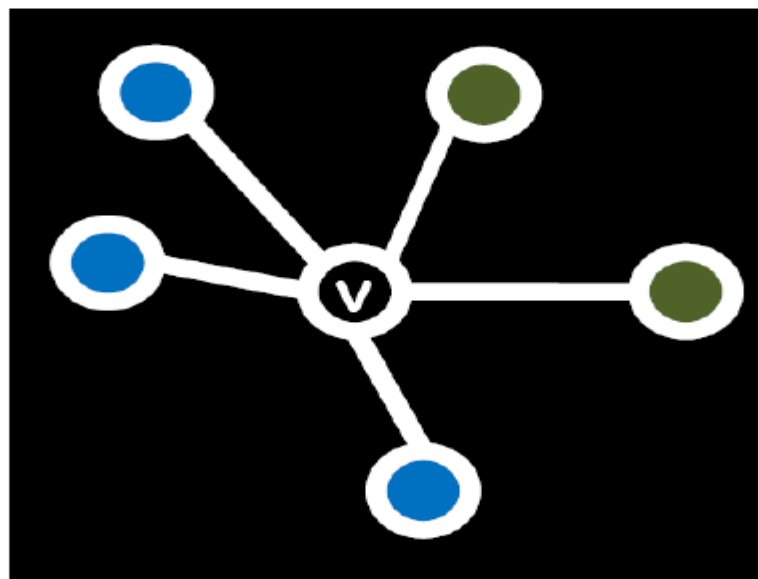
Decision-based diffusion models

Game-theoretic models of cascades

[Moore 2000]

Game theoretic models of cascades

- **Based on 2 player coordination game**
 - 2 players – each chooses technology A or B
 - Each person can only adopt **one** “behavior”, **A or B**
 - You gain more payoff if your friend has adopted the **same** behavior as you



Local view of the network of node v

Rules of the game

- **Payoff matrix:**

- If both v and w adopt behavior A , they each get payoff $a > 0$
- If v and w adopt behavior B , they reach get payoff $b > 0$
- If v and w adopt the opposite behaviors, they each get 0

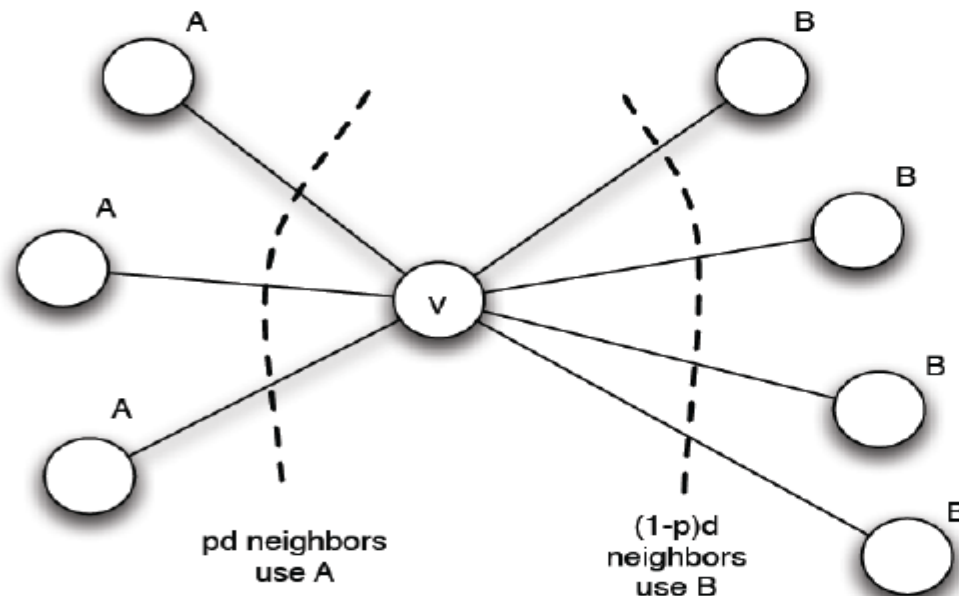


- **In some large network:**

- Each node v is playing a copy of the game with each of its neighbors
- **Payoff:** sum of node payoffs per game

| | | | |
|-----|-----|--------|--------|
| | | w | |
| | | A | B |
| v | A | a, a | $0, 0$ |
| | B | $0, 0$ | b, b |

Decision rule for node v



Threshold:

v chooses A if $p > q$

$$q = \frac{b}{a + b}$$

- Let v have d neighbors
- Assume fraction p of v 's neighbors adopt A
 - $Payoff_v = a \cdot p \cdot d$ if v chooses A
 - $= b \cdot (1-p) \cdot d$ if v chooses B
- **Thus: v chooses A if: $a \cdot p \cdot d > b \cdot (1-p) \cdot d$**

Example

- **Scenario:**

Graph where everyone starts with B.

Small set S of early adopters of A

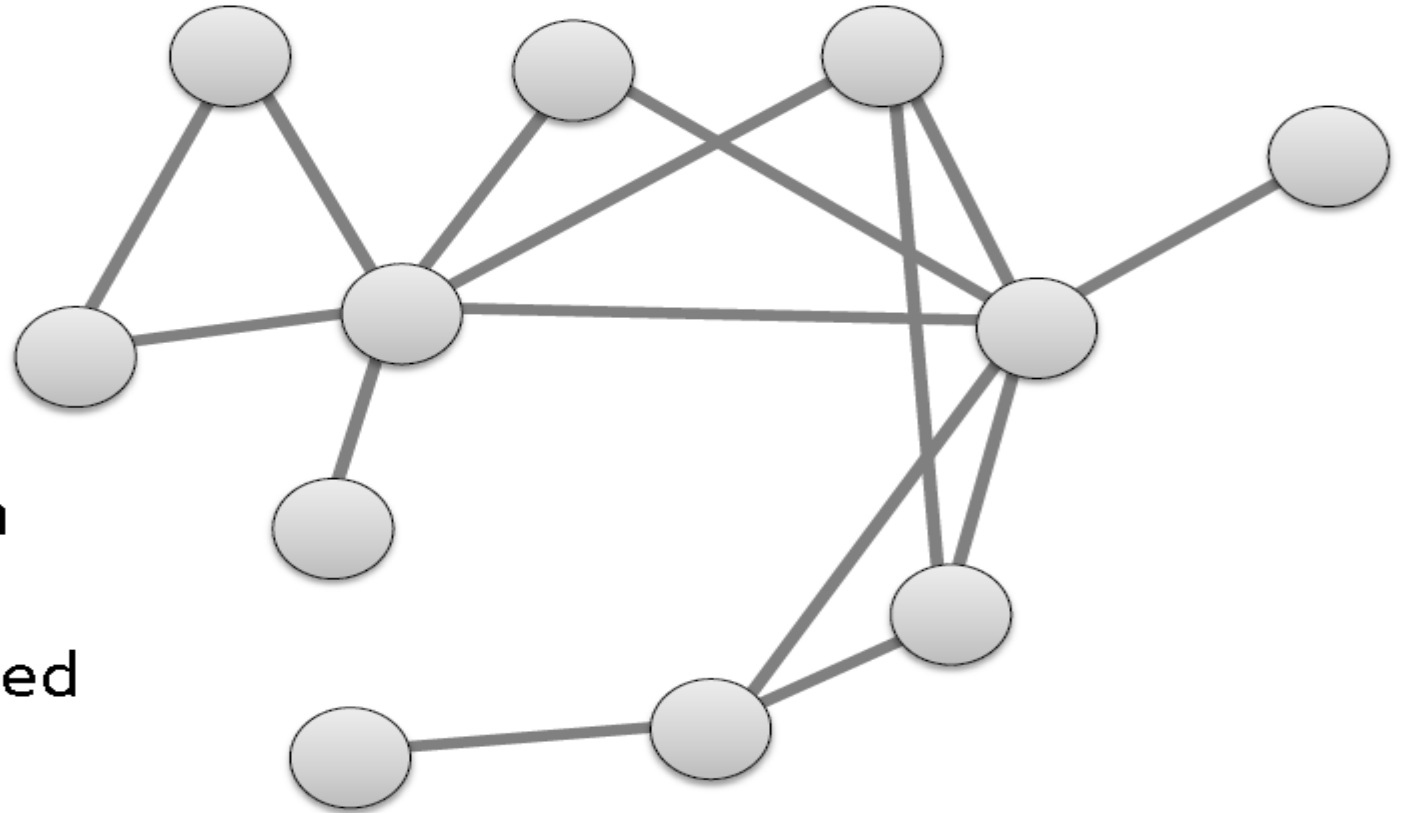
- Hard wire S – they keep using A no matter what payoffs tell them to do

- Payoffs are set in such a way that nodes say:

If at least 50% of my friends are red I'll be red

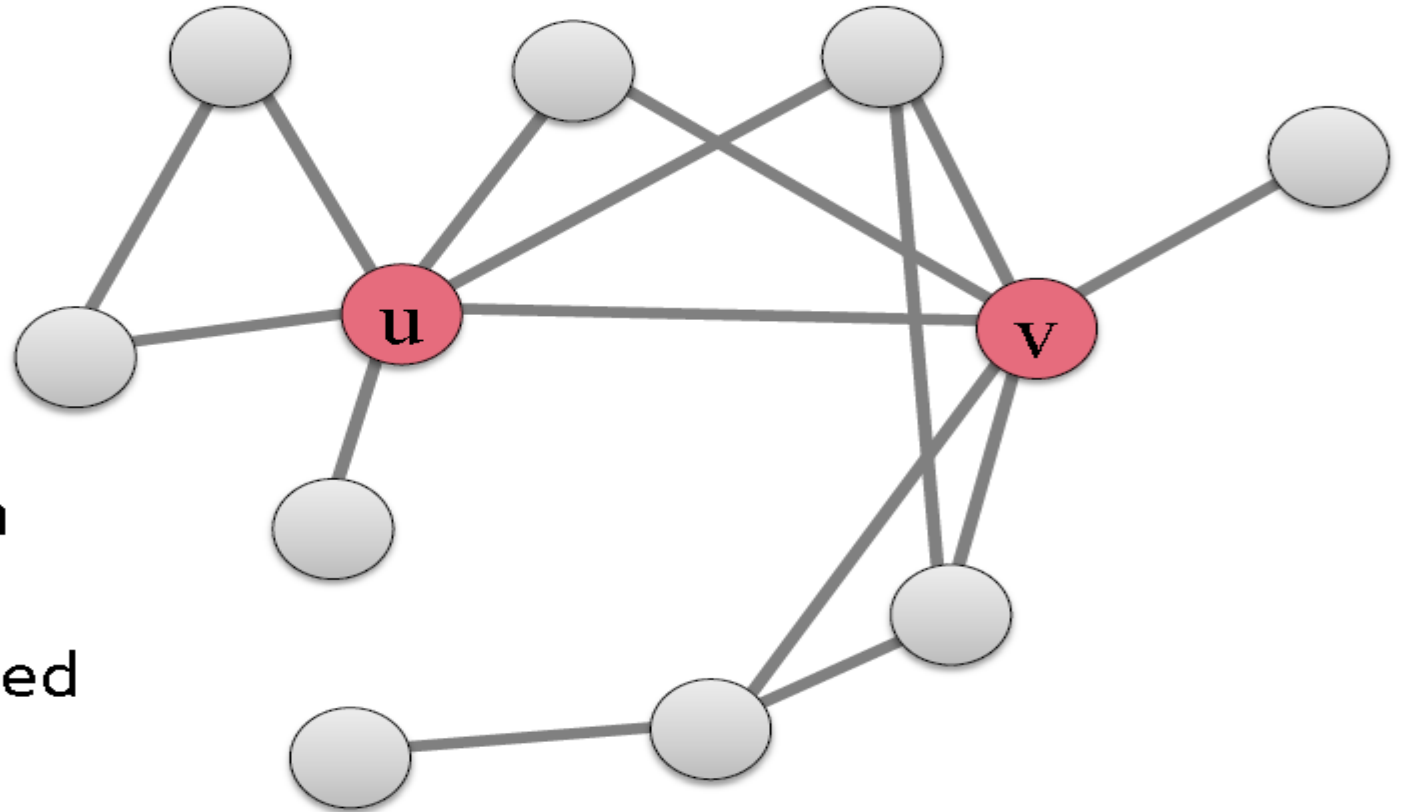
(this means: $a = b + \epsilon$)

$$S = \{u, v\}$$



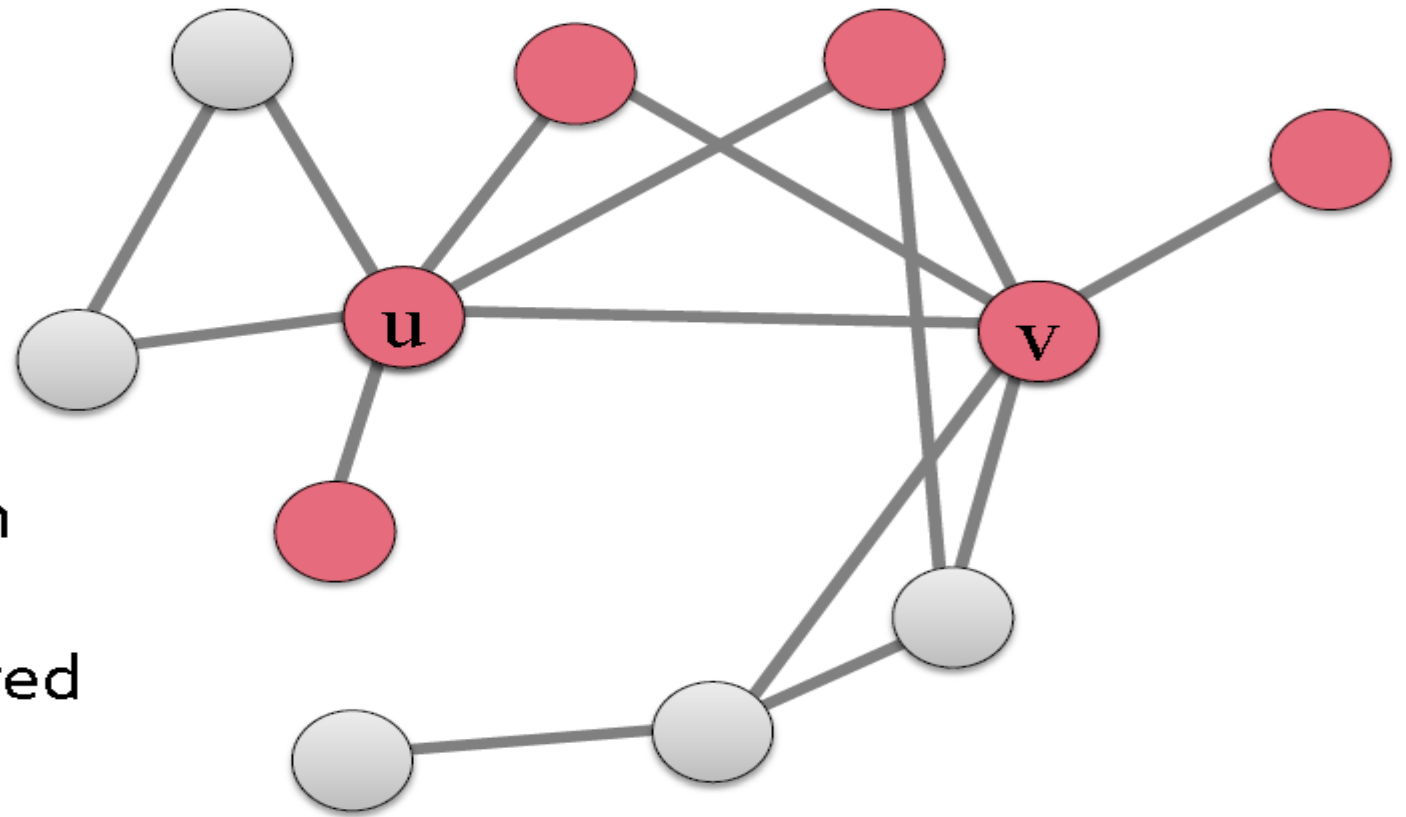
If **more** than
50% of my
friends are red
I'll be red

$$S = \{u, v\}$$



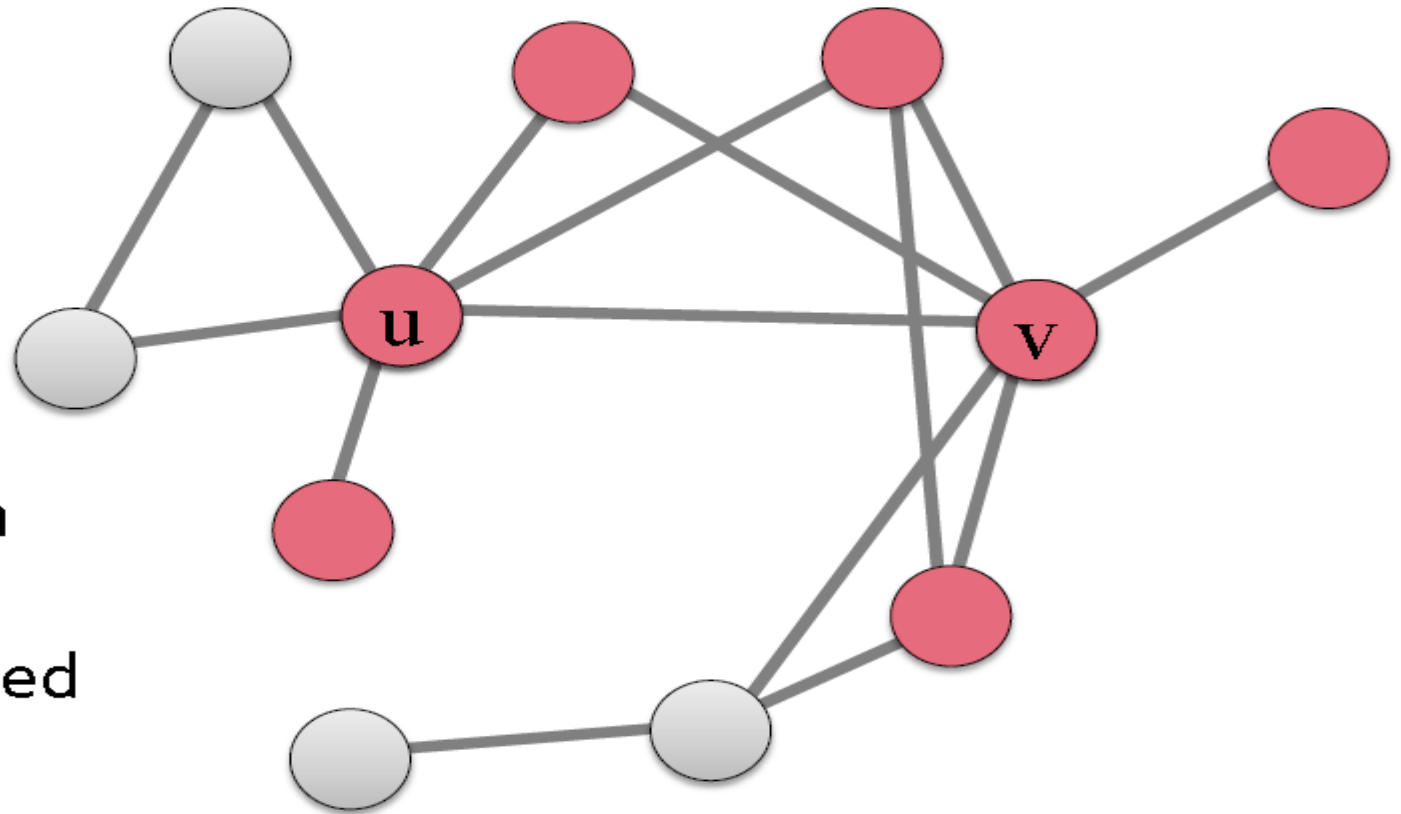
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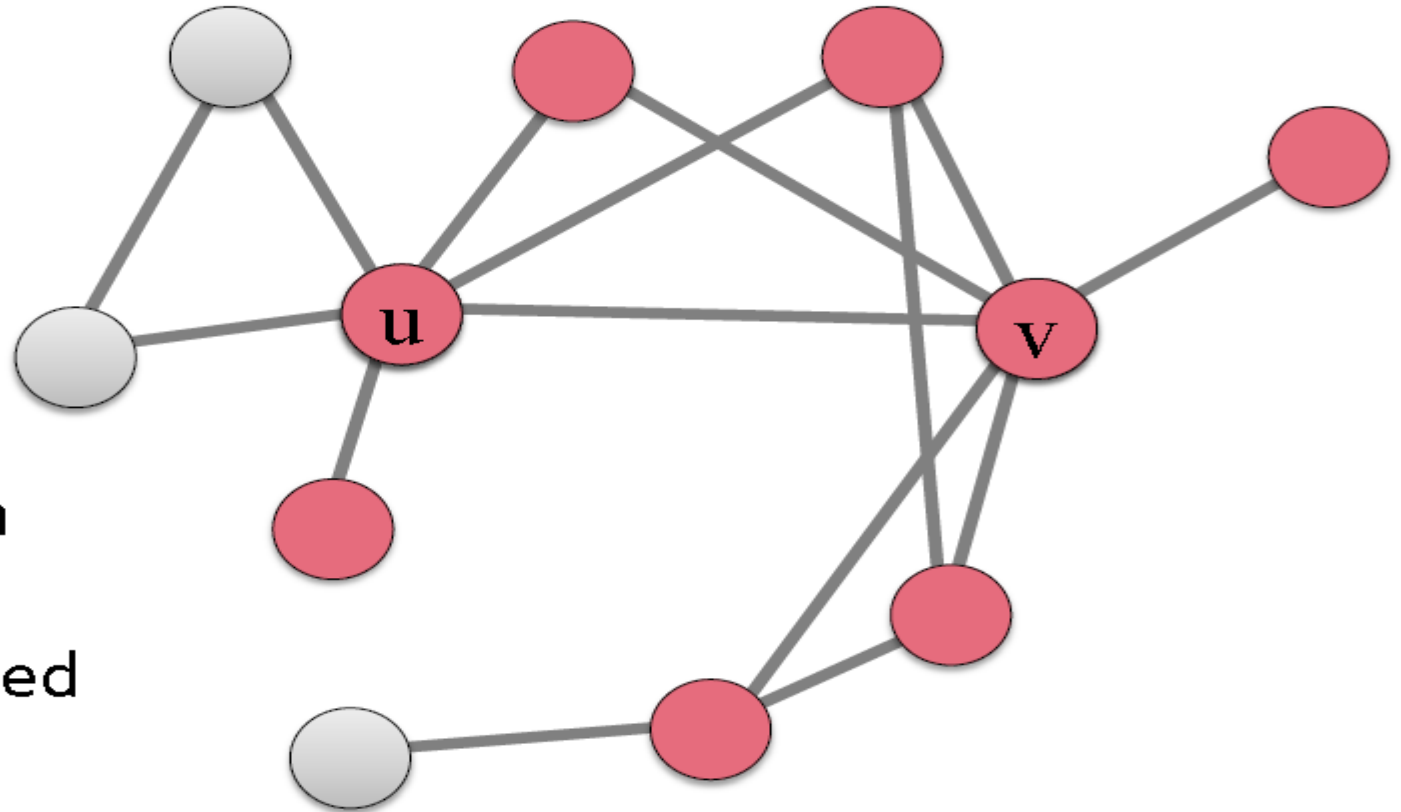
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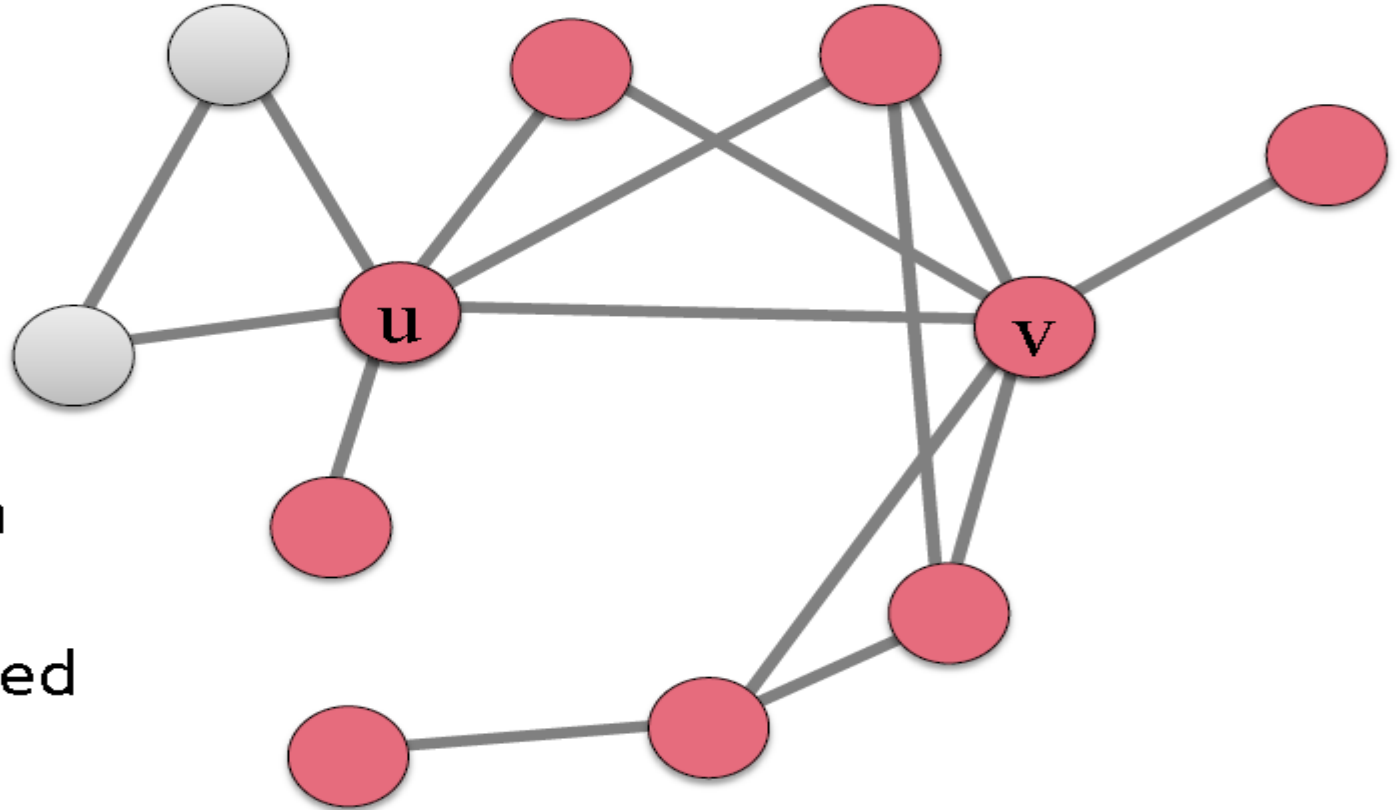
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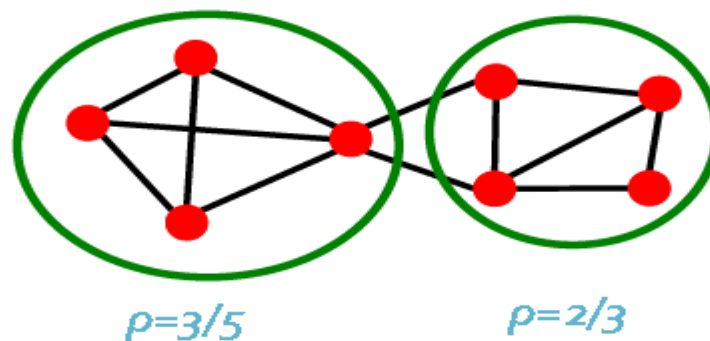
$$S = \{u, v\}$$



If **more** than
50% of my
friends are red
I'll be red

Stopping cascades

- **What prevents cascades from spreading?**
- Def: **Cluster of density ρ** is a **set of nodes C** where each node in the set has at least ρ fraction of edges in C .



Stopping cascades

- Let S be an initial set of adopters of A
- All nodes apply threshold q to decide whether to switch to A
- **Two facts:**
 - 1) If $G \setminus S$ contains a cluster of density $>(1-q)$ then S can not cause a cascade
 - 2) If S fails to create a cascade, then there is a cluster of density $>(1-q)$ in $G \setminus S$