

Introduction

Modelling parallel systems

## Linear Time Properties

state-based and linear time view

definition of linear time properties

invariants and safety

**liveness and fairness**



Regular Properties

Linear Temporal Logic

Computation-Tree Logic

Equivalences and Abstraction

**“liveness: something good will happen.”**

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e.g., **termination** for sequential programs

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e.g., **starvation freedom** for dining philosophers

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“whenever event **b** occurs then event **a**  
will occur sometimes in the future”

e.g., every **waiting process** enters eventually  
its **critical section**

## which property type?

LF2.6-2

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*here:* one just example for a formal definition  
of liveness

# Definition of liveness properties

LF2.6-DEF-LIVENESS

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Let  $E$  be an LT property over  $AP$ , i.e.,  $E \subseteq (2^{AP})^\omega$ .

$E$  is called a **liveness property** if each finite word over  $AP$  can be extended to an infinite word in  $E$

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$$\mathit{pref}(E) = (2^{AP})^+$$

*recall:*  $\mathit{pref}(E) =$  set of all finite, nonempty prefixes of words in  $E$

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Examples:

- each process will **eventually** enter its critical section
- each process will enter its critical section **infinitely often**
- whenever a process has requested its critical section then it will **eventually** enter its critical section

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$\forall i \in \{1, \dots, n\} \forall j \geq 0. \text{wait}_i \in A_j$

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## Recall: safety properties, prefix closure

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# Decomposition theorem

LF2.6-DECOMP-THM

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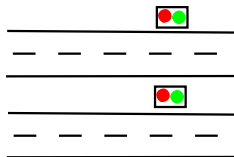
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If  $E$  is a **safety** property too, then  $\text{cl}(E) = E$ .  
Hence  $E = \text{cl}(E) = (2^{AP})^\omega$ .

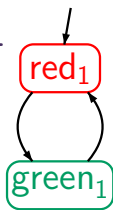
liveness properties are often violated  
although we expect them to hold

# Two independent traffic lights

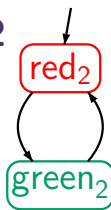
LF2.6-3



light 1

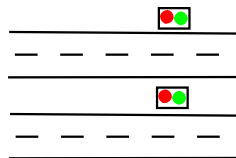


light 2

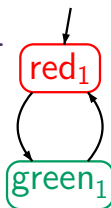


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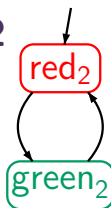
LF2.6-3



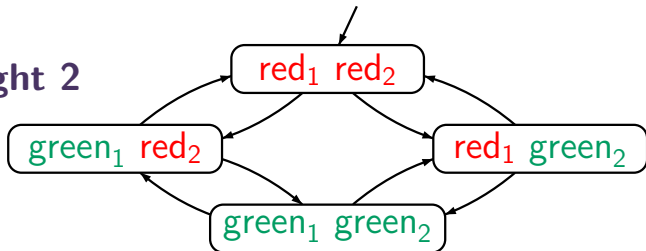
light 1



light 2

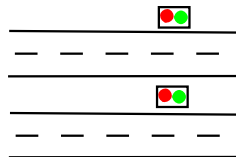


light 1 ||| light 2

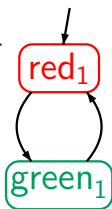


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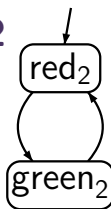
LF2.6-3



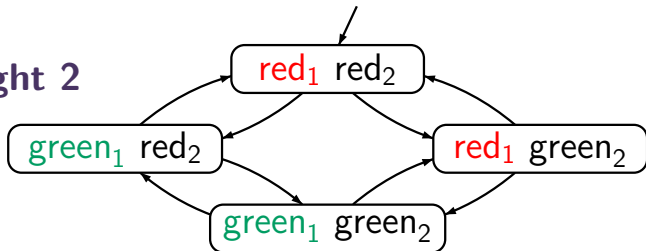
light 1



light 2



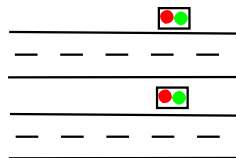
light 1 ||| light 2



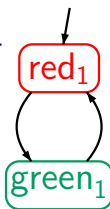
light 1 ||| light 2  $\not\equiv$  "infinitely often  $green_1$ "

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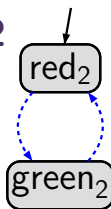
LF2.6-3



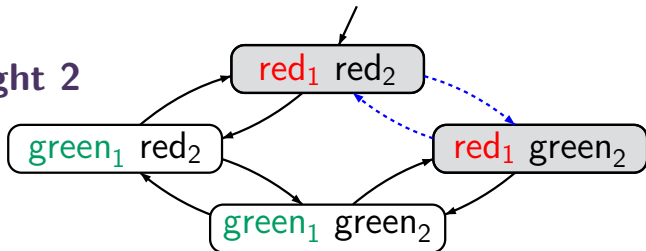
light 1



light 2



light 1 ||| light 2

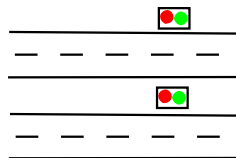


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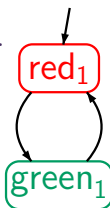


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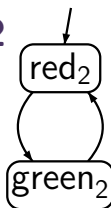
LF2.6-3



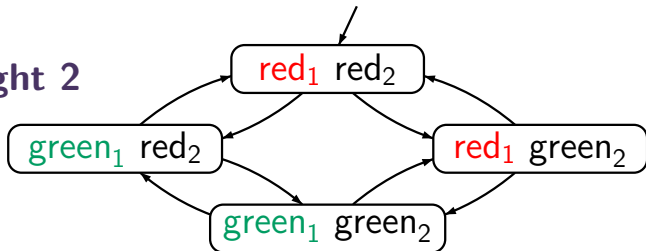
light 1



light 2



light 1 ||| light 2

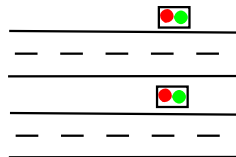


light 1 ||| light 2  $\not\models$  “infinitely often  $green_1$ ”

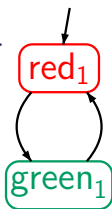
although light 1  $\models$  “infinitely often  $green_1$ ”

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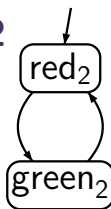
LF2.6-3



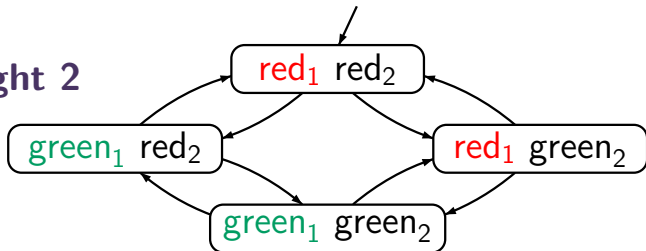
light 1



light 2



light 1 ||| light 2



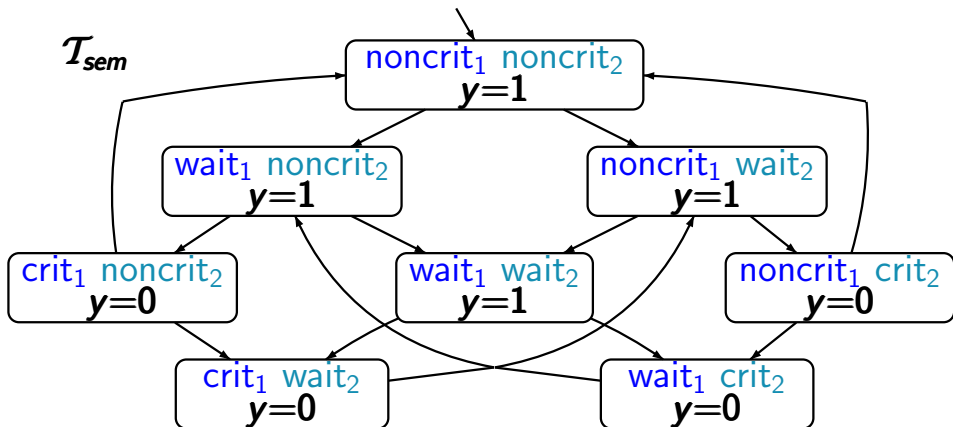
light 1 ||| light 2  $\not\equiv$  “infinitely often *green<sub>1</sub>*”

interleaving is completely time abstract !

# Mutual exclusion (semaphore)

LF2.6-4

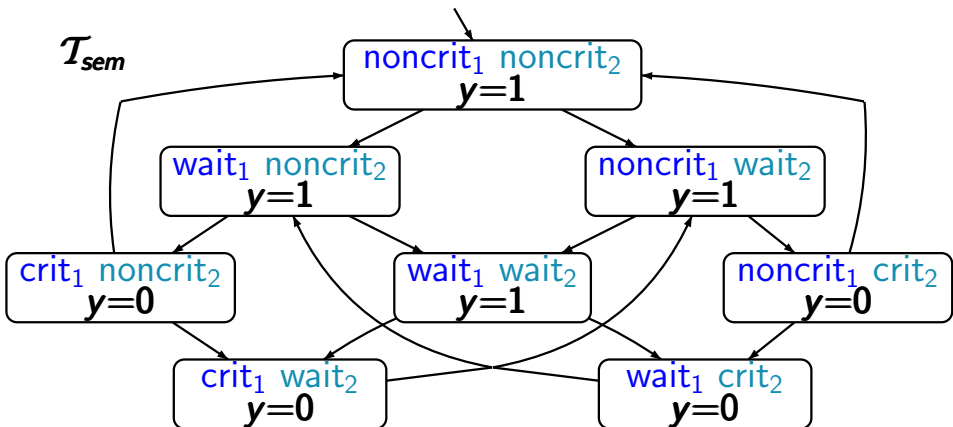
$T_{sem}$



# Mutual exclusion (semaphore)

LF2.6-4

$\mathcal{T}_{sem}$

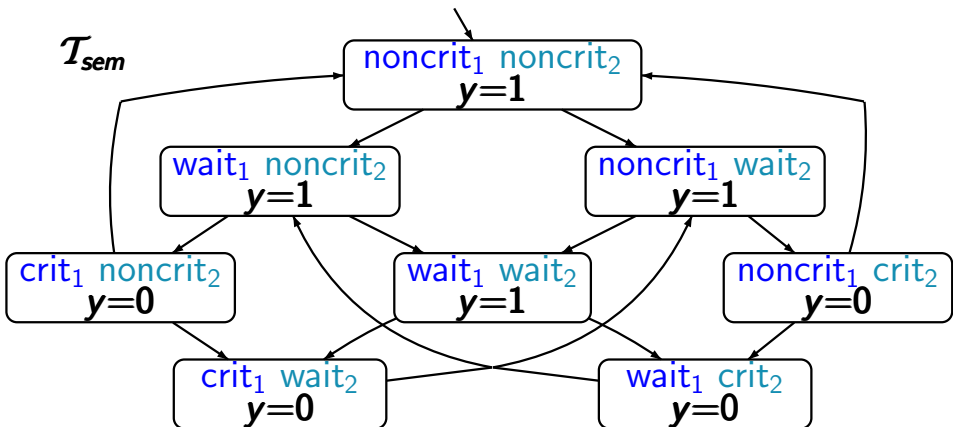


liveness property  $\hat{=}$  "each waiting process will eventually enter its critical section"

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LF2.6-4

$\mathcal{T}_{sem}$



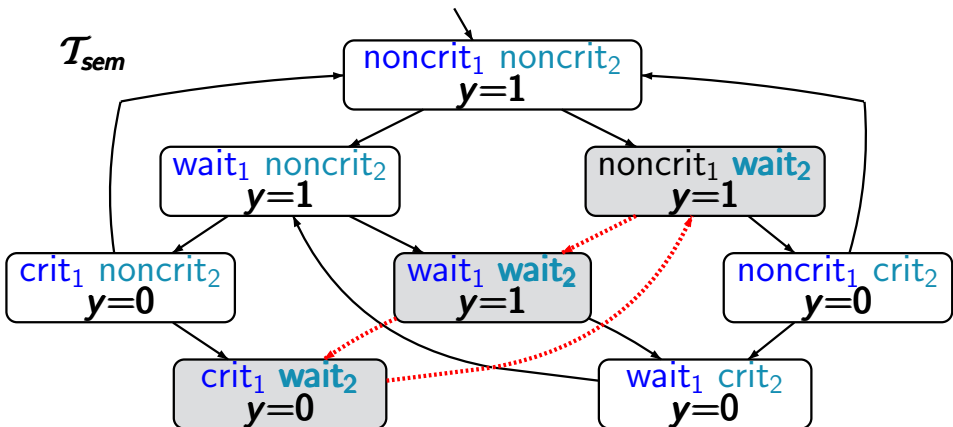
$\mathcal{T}_{sem} \not\models$

“each waiting process will eventually enter its critical section”

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LF2.6-4

$\mathcal{T}_{sem}$



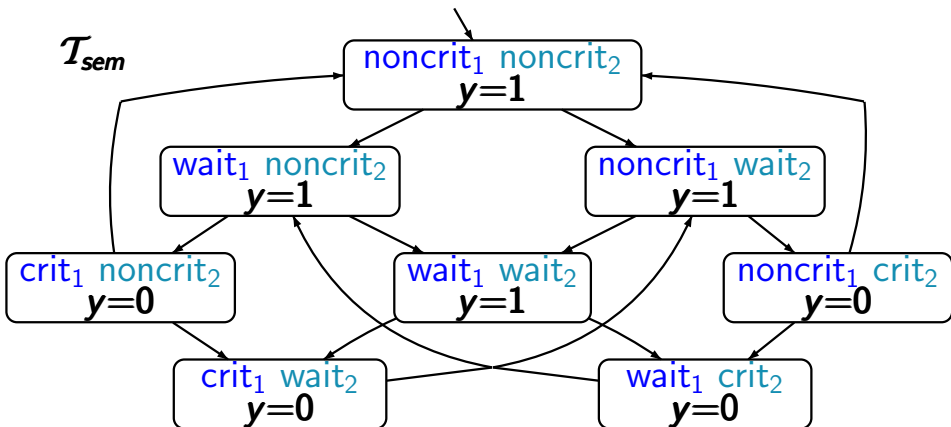
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LF2.6-4

$\mathcal{T}_{sem}$



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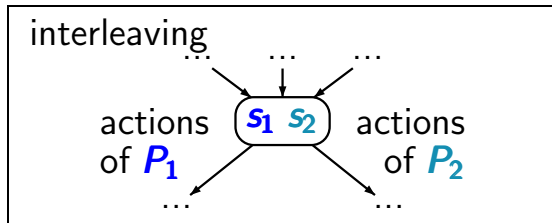
“each waiting process will eventually enter its critical section”

level of abstraction is **too coarse** !





two independent  
non-communicating  
processes  $P_1$  |||  $P_2$



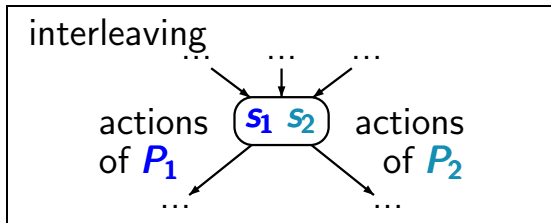
possible interleavings:

$P_1 P_2 P_2 P_1 P_1 P_1 P_2 P_1 P_2 P_2 P_2 P_1 P_1 \dots$   
 $P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 \dots$

# Process fairness

LF2.6-5

two independent  
non-communicating  
processes  $P_1$  |||  $P_2$



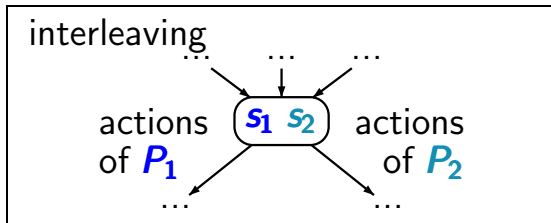
possible interleavings:

$P_1 P_2 P_2 P_1 P_1 P_1 P_2 P_1 P_2 P_2 P_2 P_1 P_1 \dots$   
 $P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 \dots$   
 $P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 \dots$

# Process fairness

LF2.6-5

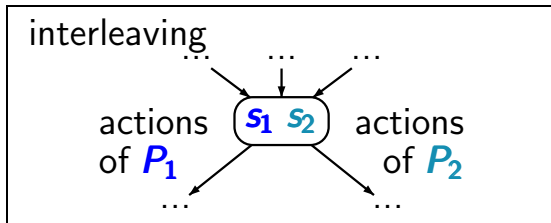
two independent  
non-communicating  
processes  $P_1$  |||  $P_2$



possible interleavings:

$P_1 P_2 P_2 P_1 P_1 P_1 P_2 P_1 P_2 P_2 P_2 P_1 P_1 \dots$  fair  
 $P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 \dots$  fair  
 $P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 \dots$  unfair

two independent  
non-communicating  
processes  $P_1$  |||  $P_2$



possible interleavings:

$P_1 P_2 P_2 P_1 P_1 P_1 P_2 P_1 P_2 P_2 P_2 P_1 P_1 \dots$  fair  
 $P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 P_1 P_2 P_1 \dots$  fair  
 $P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 P_1 \dots$  unfair

process fairness assumes an appropriate resolution  
of the nondeterminism resulting from  
interleaving and competitions

- unconditional fairness
- strong fairness
- weak fairness

- unconditional fairness, e.g.,  
every process enters gets its turn infinitely often.
- strong fairness
- weak fairness

- **unconditional fairness**, e.g.,  
every process enters gets its turn **infinitely often**.
- **strong fairness**, e.g.,  
every process that is **enabled infinitely often**  
gets its turn **infinitely often**.
- **weak fairness**

- **unconditional fairness**, e.g.,  
every process enters gets its turn **infinitely often**.
- **strong fairness**, e.g.,  
every process that is **enabled infinitely often**  
gets its turn **infinitely often**.
- **weak fairness**, e.g.,  
every process that is **continuously enabled**  
from a certain time instance on,  
gets its turn **infinitely often**.





Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $A \subseteq \mathbf{Act}$  and

$\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

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we will provide conditions for

- unconditional  $A$ -fairness of  $\rho$
- strong  $A$ -fairness of  $\rho$
- weak  $A$ -fairness of  $\rho$

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using the following notations:

$$\mathbf{Act}(s_i) = \{ \beta \in \mathbf{Act} : \exists s' \text{ s.t. } s_i \xrightarrow{\beta} s' \}$$

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using the following notations:

$$\mathbf{Act}(s_i) = \{\beta \in \mathbf{Act} : \exists s' \text{ s.t. } s_i \xrightarrow{\beta} s'\}$$
$$\overset{\infty}{\exists} \hat{=} \text{“there exists infinitely many ...”}$$

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $A \subseteq \mathbf{Act}$  and

$\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

we will provide conditions for

- unconditional  $A$ -fairness of  $\rho$
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- weak  $A$ -fairness of  $\rho$

using the following notations:

$$\begin{aligned} \mathbf{Act}(s_i) &= \{ \beta \in \mathbf{Act} : \exists s' \text{ s.t. } s_i \xrightarrow{\beta} s' \} \\ \infty \exists &\hat{=} \text{“there exists infinitely many ...”} \\ \infty \forall &\hat{=} \text{“for all, but finitely many ...”} \end{aligned}$$

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and

$\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  
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- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists i \geq 0. \alpha_i \in \mathbf{A}$



“actions in  $\mathbf{A}$  will be taken infinitely many times”



Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  
 $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists i \geq 0. \alpha_i \in \mathbf{A}$
- $\rho$  is strongly  $\mathbf{A}$ -fair, if

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  
 $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$
- $\rho$  is strongly  $\mathbf{A}$ -fair, if

$$\exists^{\infty} i \geq 0. \mathbf{A} \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$$

“If infinitely many times some action in  $\mathbf{A}$  is enabled, then actions in  $\mathbf{A}$  will be taken infinitely many times.”

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $A \subseteq \mathbf{Act}$  and  
 $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $A$ -fair, if  $\exists i \geq 0. \alpha_i \in A$
- $\rho$  is strongly  $A$ -fair, if
$$\exists i \geq 0. A \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists i \geq 0. \alpha_i \in A$$
- $\rho$  is weakly  $A$ -fair, if

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  
 $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists i \geq 0. \alpha_i \in \mathbf{A}$

- $\rho$  is strongly  $\mathbf{A}$ -fair, if

$$\exists i \geq 0. \mathbf{A} \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists i \geq 0. \alpha_i \in \mathbf{A}$$

- $\rho$  is weakly  $\mathbf{A}$ -fair, if

$$\forall i \geq 0. \mathbf{A} \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists i \geq 0. \alpha_i \in \mathbf{A}$$

“If from some moment, actions in  $\mathbf{A}$  are enabled, then actions in  $\mathbf{A}$  will be taken infinitely many times.”

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  
 $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$

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unconditionally $\mathbf{A}$ -fair $\implies$ strongly $\mathbf{A}$ -fair $\implies$ weakly $\mathbf{A}$ -fair
---

Let  $\mathcal{T}$  be a TS with action-set  $\mathbf{Act}$ ,  $\mathbf{A} \subseteq \mathbf{Act}$  and  $\rho = s_0 \xrightarrow{\alpha_0} s_1 \xrightarrow{\alpha_1} s_2 \xrightarrow{\alpha_2} \dots$  an infinite execution fragment

- $\rho$  is unconditionally  $\mathbf{A}$ -fair, if  $\exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$

- $\rho$  is strongly  $\mathbf{A}$ -fair, if

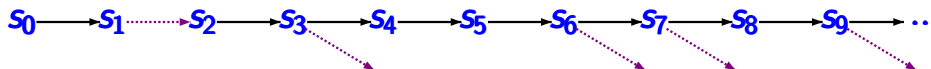
$$\exists^{\infty} i \geq 0. \mathbf{A} \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$$

- $\rho$  is weakly  $\mathbf{A}$ -fair, if

$$\forall^{\infty} i \geq 0. \mathbf{A} \cap \mathbf{Act}(s_i) \neq \emptyset \implies \exists^{\infty} i \geq 0. \alpha_i \in \mathbf{A}$$

unconditionally $\mathbf{A}$ -fair $\implies$ strongly $\mathbf{A}$ -fair $\implies$ weakly $\mathbf{A}$ -fair
---

strong **A**-fairness is *violated* if



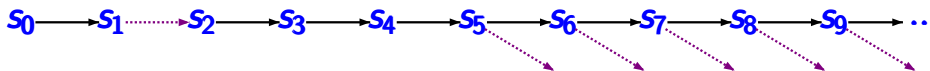
- no **A**-actions are executed from a certain moment
- **A**-actions are enabled infinitely many times

strong **A**-fairness is *violated* if



- no **A**-actions are executed from a certain moment
- **A**-actions are **enabled infinitely many times**

weak **A**-fairness is *violated* if

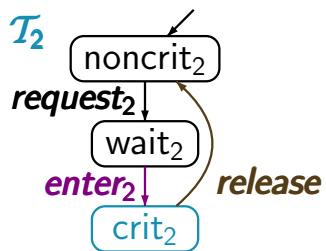
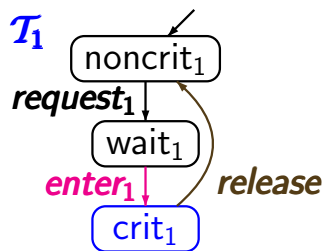


- no **A**-actions are executed from a certain moment
- **A**-actions are **continuously enabled** from some moment on



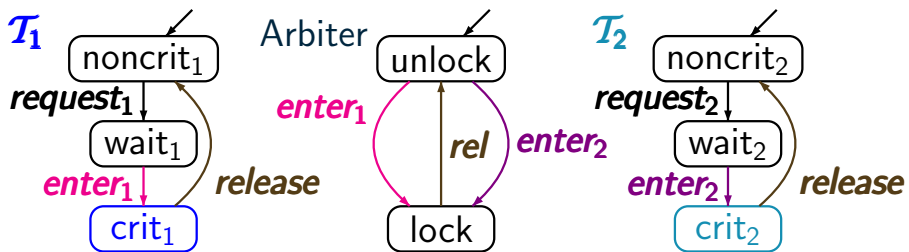
# Mutual exclusion with arbiter

LF2.6-9



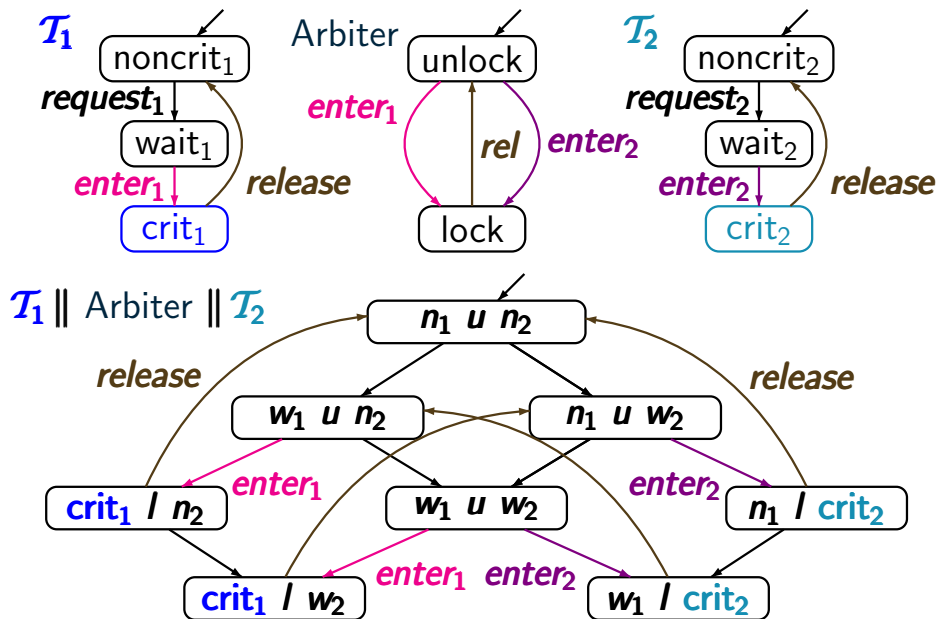
# Mutual exclusion with arbiter

LF2.6-9



# Mutual exclusion with arbiter

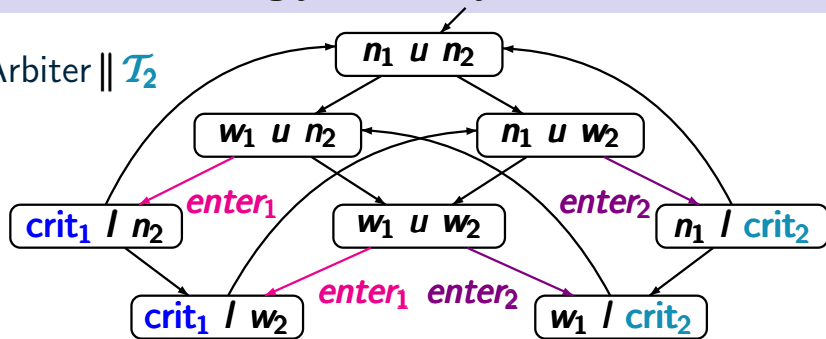
LF2.6-9



# Unconditional, strongly or weakly fair?

LF2.6-10

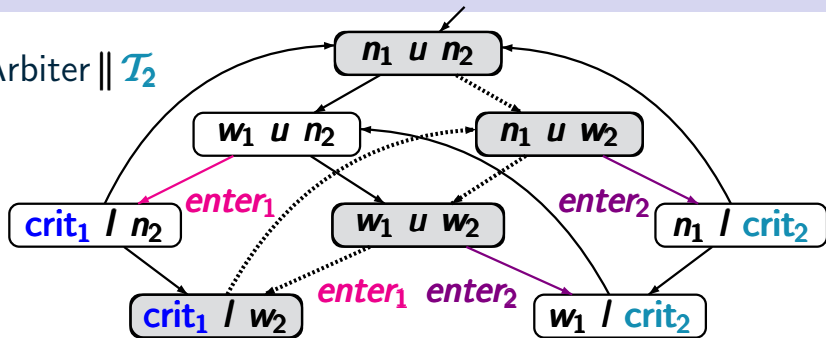
$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action set  $A = \{\text{enter}_1\}$ :

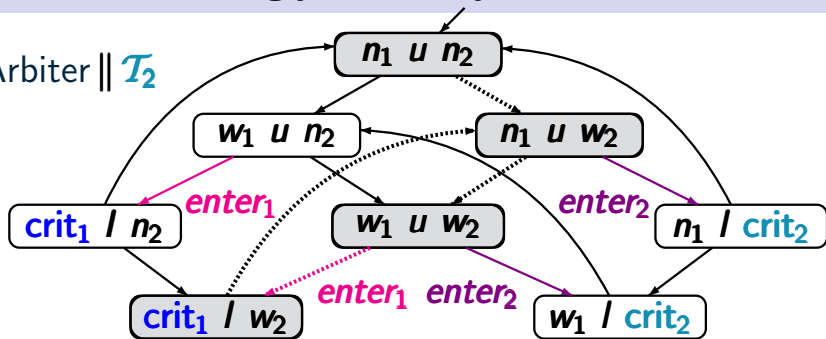
$$\langle n_1, u, n_2 \rangle \rightarrow \left( \langle n_1, u, w_2 \rangle \rightarrow \langle w_1, u, w_2 \rangle \rightarrow \langle \text{crit}_1, l, w_2 \rangle \right)^\omega$$

- unconditional  $A$ -fairness:
- strong  $A$ -fairness:
- weak  $A$ -fairness:

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action set  $A = \{\text{enter}_1\}$ :

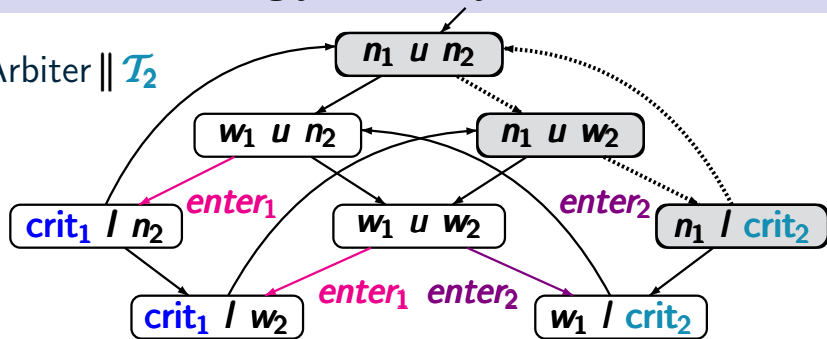
$$\langle n_1, u, n_2 \rangle \rightarrow \left( \langle n_1, u, w_2 \rangle \rightarrow \langle w_1, u, w_2 \rangle \rightarrow \langle \text{crit}_1, l, w_2 \rangle \right)^\omega$$

- unconditional  $A$ -fairness: **yes**
- strong  $A$ -fairness: **yes** ← unconditionally fair
- weak  $A$ -fairness: **yes** ← unconditionally fair

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action-set  $A = \{enter_1\}$ :

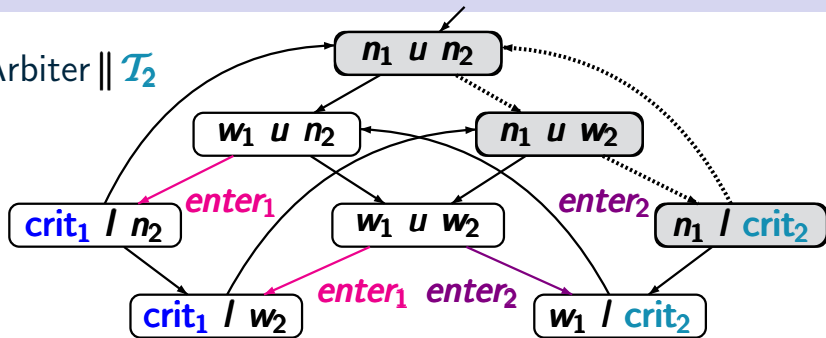
$$\left( \langle n_1, u, n_2 \rangle \rightarrow \langle n_1, u, w_2 \rangle \rightarrow \langle n_1, l, crit_2 \rangle \right)^\omega$$

- unconditional  $A$ -fairness:
- strong  $A$ -fairness:
- weak  $A$ -fairness:

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action-set  $A = \{enter_1\}$ :

$$\left( \langle n_1, u, n_2 \rangle \rightarrow \langle n_1, u, w_2 \rangle \rightarrow \langle n_1, l, crit_2 \rangle \right)^\omega$$

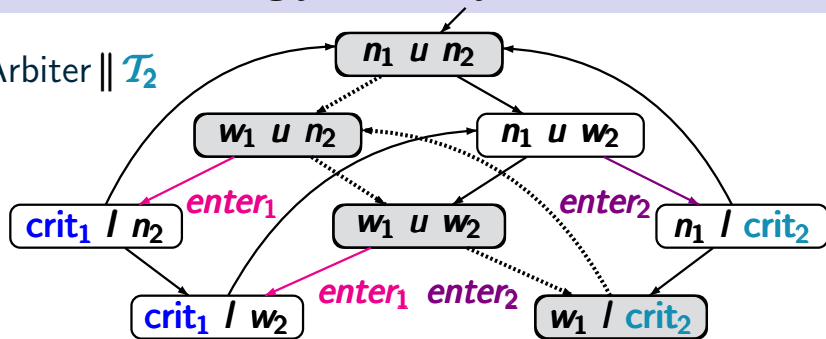
- unconditional  $A$ -fairness: **no**
- strong  $A$ -fairness: **yes**  $\leftarrow A$  never enabled
- weak  $A$ -fairness: **yes**  $\leftarrow$  strongly  $A$ -fair



# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action-set  $A = \{enter_1\}$ :

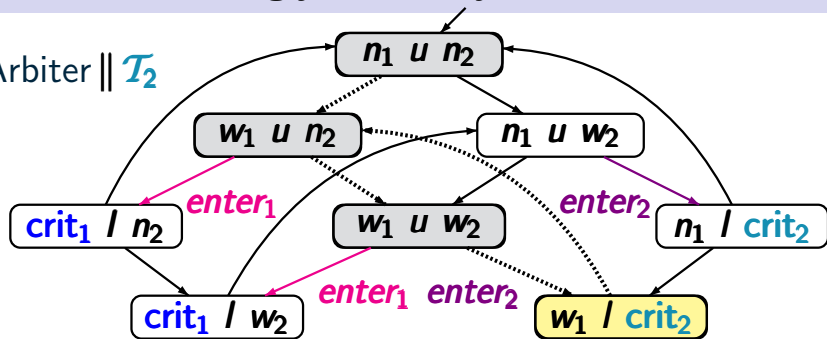
$$\langle n_1, u, n_2 \rangle \rightarrow \left( \langle w_1, u, n_2 \rangle \rightarrow \langle w_1, u, w_2 \rangle \rightarrow \langle n_1, l, crit_2 \rangle \right)^w$$

- unconditional  $A$ -fairness:
- strong  $A$ -fairness:
- weak  $A$ -fairness:

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action-set  $A = \{\text{enter}_1\}$ :

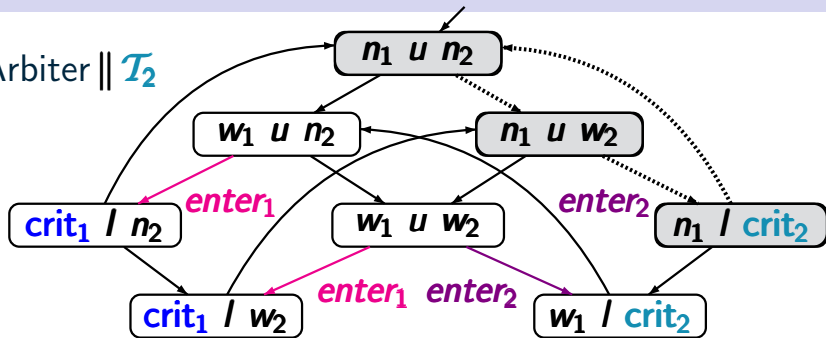
$$\langle n_1, u, n_2 \rangle \rightarrow \left( \langle w_1, u, n_2 \rangle \rightarrow \langle w_1, u, w_2 \rangle \rightarrow \langle n_1, l, \text{crit}_2 \rangle \right)^w$$

- unconditional  $A$ -fairness: **no**
- strong  $A$ -fairness: **no**
- weak  $A$ -fairness: **yes**

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action set  $A = \{enter_1, enter_2\}$ :

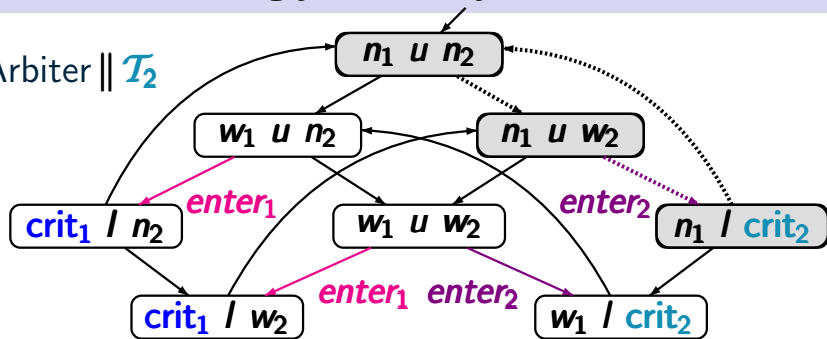
$$\left( \langle n_1, u, n_2 \rangle \rightarrow \langle n_1, u, w_2 \rangle \rightarrow \langle n_1, u, crit_2 \rangle \right)^\omega$$

- unconditional  $A$ -fairness:
- strong  $A$ -fairness:
- weak  $A$ -fairness:

# Unconditional, strongly or weakly fair?

LF2.6-10

$\mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$



fairness for action set  $A = \{enter_1, enter_2\}$ :

$$\left( \langle n_1, u, n_2 \rangle \rightarrow \langle n_1, u, w_2 \rangle \rightarrow \langle n_1, u, crit_2 \rangle \right)^{\omega}$$

- unconditional  $A$ -fairness: **yes**
- strong  $A$ -fairness: **yes**
- weak  $A$ -fairness: **yes**

# Action-based fairness assumptions

LF2.6-DEF-FAIRNESS-ASSUMPTION

Let  $\mathcal{T}$  be a transition system with action-set  $Act$ .  
A fairness assumption for  $\mathcal{T}$  is a triple

$$\mathcal{F} = (\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak})$$

where  $\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak} \subseteq 2^{Act}$ .

Let  $\mathcal{T}$  be a transition system with action-set  $Act$ .  
A fairness assumption for  $\mathcal{T}$  is a triple

$$\mathcal{F} = (\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak})$$

where  $\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak} \subseteq 2^{Act}$ .

An execution  $\rho$  is called  $\mathcal{F}$ -fair iff

- $\rho$  is unconditionally  $A$ -fair for all  $A \in \mathcal{F}_{ucond}$
- $\rho$  is strongly  $A$ -fair for all  $A \in \mathcal{F}_{strong}$
- $\rho$  is weakly  $A$ -fair for all  $A \in \mathcal{F}_{weak}$

Let  $\mathcal{T}$  be a transition system with action-set  $Act$ .  
A fairness assumption for  $\mathcal{T}$  is a triple

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- $\rho$  is unconditionally  $A$ -fair for all  $A \in \mathcal{F}_{ucond}$
- $\rho$  is strongly  $A$ -fair for all  $A \in \mathcal{F}_{strong}$
- $\rho$  is weakly  $A$ -fair for all  $A \in \mathcal{F}_{weak}$

$$FairTraces_{\mathcal{F}}(\mathcal{T}) \stackrel{\text{def}}{=} \{ trace(\rho) : \rho \text{ is a } \mathcal{F}\text{-fair execution of } \mathcal{T} \}$$





A fairness assumption for  $\mathcal{T}$  is a triple

$$\mathcal{F} = (\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak})$$

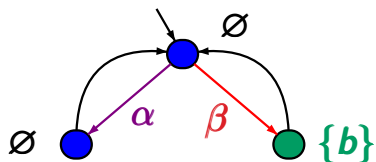
where  $\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak} \subseteq 2^{Act}$ .

An execution  $\rho$  is called  $\mathcal{F}$ -fair iff

- $\rho$  is unconditionally  $A$ -fair for all  $A \in \mathcal{F}_{ucond}$
- $\rho$  is strongly  $A$ -fair for all  $A \in \mathcal{F}_{strong}$
- $\rho$  is weakly  $A$ -fair for all  $A \in \mathcal{F}_{weak}$

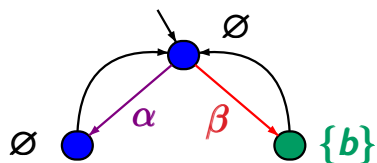
If  $\mathcal{T}$  is a TS and  $E$  a LT property over  $AP$  then:

$$\mathcal{T} \models_{\mathcal{F}} E \iff \text{FairTraces}_{\mathcal{F}}(\mathcal{T}) \subseteq E$$



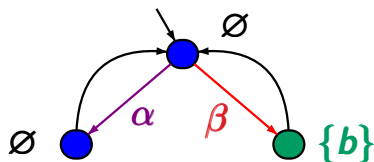
fairness assumption  $\mathcal{F}$

- no unconditional fairness condition
- strong fairness for  $\{\alpha, \beta\}$
- no weak fairness condition



fairness assumption  $\mathcal{F}$

- no unconditional fairness condition  $\leftarrow \mathcal{F}_{ucond} = \emptyset$
- strong fairness for  $\{\alpha, \beta\}$   $\leftarrow \mathcal{F}_{strong} = \{\{\alpha, \beta\}\}$
- no weak fairness condition  $\leftarrow \mathcal{F}_{weak} = \emptyset$



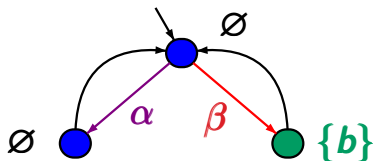
$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?

fairness assumption  $\mathcal{F}$

- no unconditional fairness condition  $\leftarrow \mathcal{F}_{ucond} = \emptyset$
- strong fairness for  $\{\alpha, \beta\}$   $\leftarrow \mathcal{F}_{strong} = \{\{\alpha, \beta\}\}$
- no weak fairness condition  $\leftarrow \mathcal{F}_{weak} = \emptyset$

## Example: fair satisfaction relation

LF2.6-11



$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?

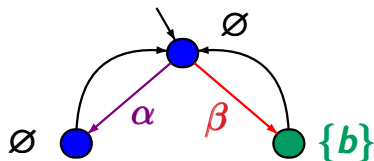
answer: **no**

fairness assumption  $\mathcal{F}$

- no unconditional fairness condition  $\leftarrow \mathcal{F}_{ucond} = \emptyset$
- strong fairness for  $\{\alpha, \beta\}$   $\leftarrow \mathcal{F}_{strong} = \{\{\alpha, \beta\}\}$
- no weak fairness condition  $\leftarrow \mathcal{F}_{weak} = \emptyset$

# Example: fair satisfaction relation

LF2.6-11

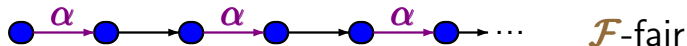


$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?

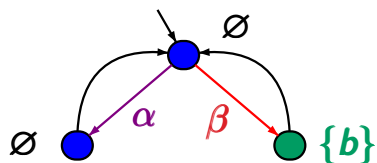
answer: **no**

fairness assumption  $\mathcal{F}$

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actions in  $\{\alpha, \beta\}$  are executed infinitely many times



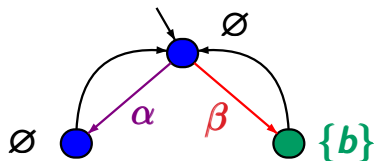
fairness assumption  $\mathcal{F}$

- strong fairness for  $\alpha$
- weak fairness for  $\beta$
- no unconditional fairness assumption

$$\leftarrow \mathcal{F}_{strong} = \{\{\alpha\}\}$$

$$\leftarrow \mathcal{F}_{weak} = \{\{\beta\}\}$$





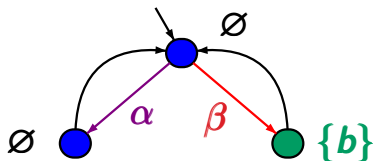
$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?

fairness assumption  $\mathcal{F}$

- strong fairness for  $\alpha$
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$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?

answer: **no**

fairness assumption  $\mathcal{F}$

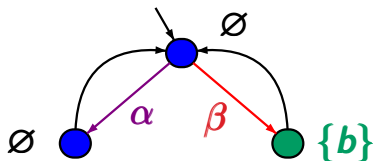
- strong fairness for  $\alpha$
- weak fairness for  $\beta$
- no unconditional fairness assumption

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# Example: fair satisfaction relation

LF2.6-12



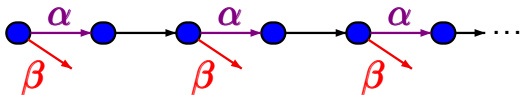
$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ” ?  
answer: **no**

fairness assumption  $\mathcal{F}$

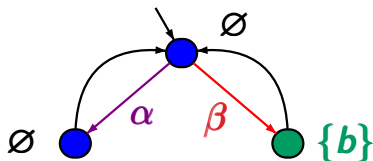
- strong fairness for  $\alpha$
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$\leftarrow \mathcal{F}_{strong} = \{\{\alpha\}\}$

$\leftarrow \mathcal{F}_{weak} = \{\{\beta\}\}$



$\mathcal{F}$ -fair



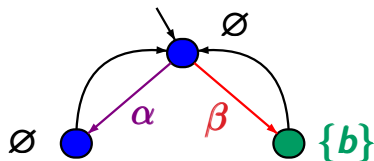
$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ”

fairness assumption  $\mathcal{F}$

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# Example: fair satisfaction relation

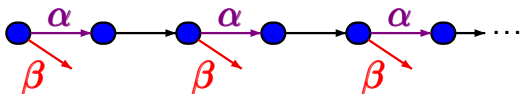
LF2.6-12A



$\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $b$ ”

fairness assumption  $\mathcal{F}$

- strong fairness for  $\beta$   $\leftarrow \mathcal{F}_{strong} = \{\{\beta\}\}$
- no weak fairness assumption
- no unconditional fairness assumption



is not  $\mathcal{F}$ -fair

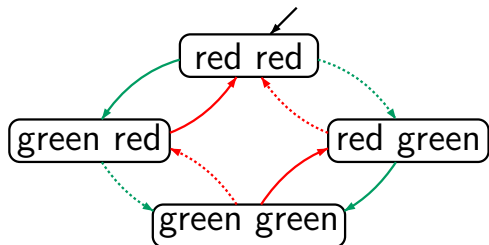
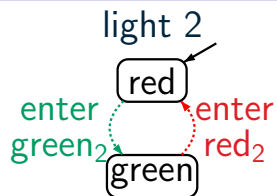
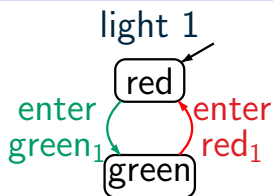
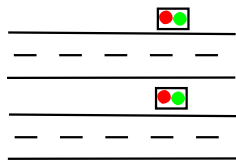
# Which type of fairness?

LF2.6-13A

fairness assumptions should be  
as weak as possible

# Two independent traffic lights

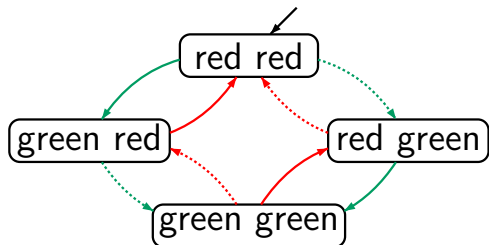
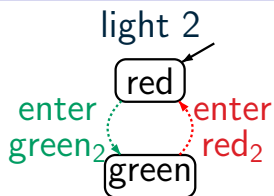
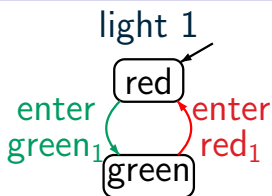
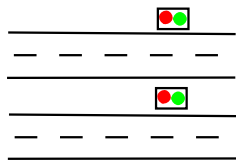
LF2.6-13





# Two independent traffic lights

LF2.6-13



fairness assumption  $\mathcal{F}$ :

$\mathcal{F}_{ucond} = ?$

$\mathcal{F}_{strong} = ?$

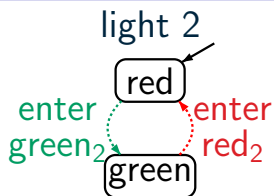
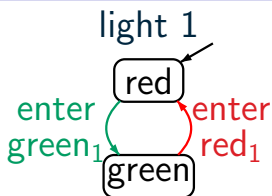
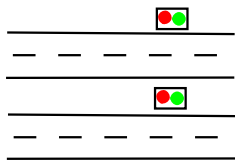
$\mathcal{F}_{weak} = ?$

light 1 ||| light 2  $\models_{\mathcal{F}} E$

$E \hat{=} \text{"both lights are infinitely often green"}$

# Two independent traffic lights

LF2.6-13



$A_1$  = actions of light 1

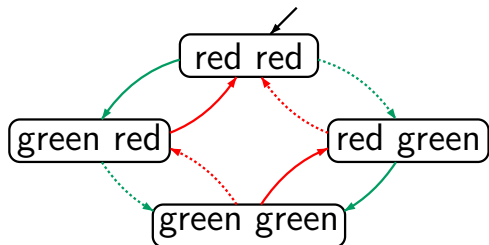
$A_2$  = actions of light 2

fairness assumption  $\mathcal{F}$ :

$\mathcal{F}_{ucond} = ?$

$\mathcal{F}_{strong} = ?$

$\mathcal{F}_{weak} = ?$

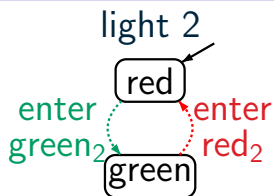
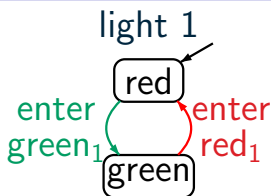
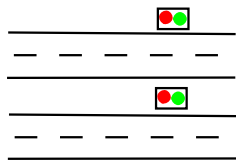


light 1 ||| light 2  $\models_{\mathcal{F}} E$

$E \hat{=}$  "both lights are infinitely often green"

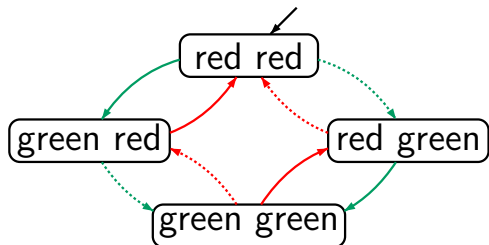
# Two independent traffic lights

LF2.6-13



$A_1$  = actions of light 1

$A_2$  = actions of light 2



fairness assumption  $\mathcal{F}$ :

$\mathcal{F}_{ucond} = \emptyset$

$\mathcal{F}_{strong} = \emptyset$

$\mathcal{F}_{weak} = \{A_1, A_2\}$

light 1 ||| light 2  $\models_{\mathcal{F}} E$

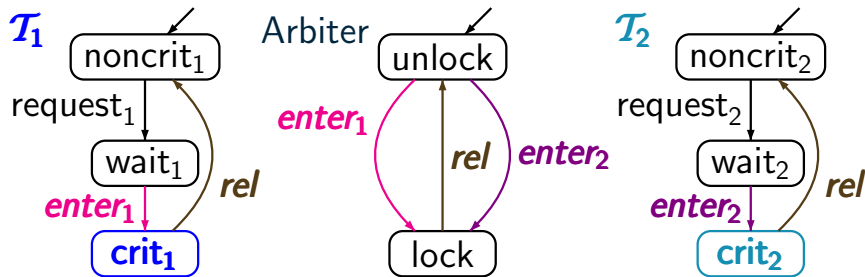
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$$\mathcal{T} = \mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$$

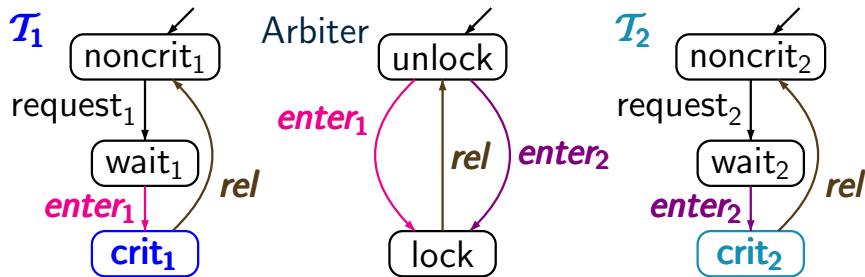
# Example: MUTEX with fair arbiter

LF2.6-15

$$\mathcal{T} = \mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$$



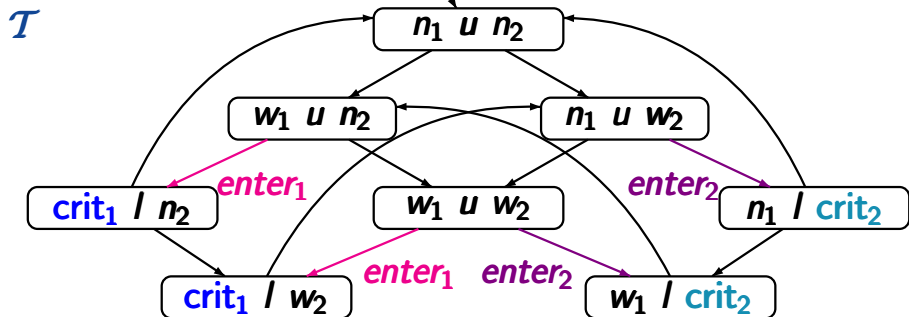
$$\mathcal{T} = \mathcal{T}_1 \parallel \text{Arbiter} \parallel \mathcal{T}_2$$



$\mathcal{T}_1$  and  $\mathcal{T}_2$  compete to communicate with the arbiter by means of the actions **enter<sub>1</sub>** and **enter<sub>2</sub>**, respectively

# Example: MUTEX with fair arbiter

LF2.6-15



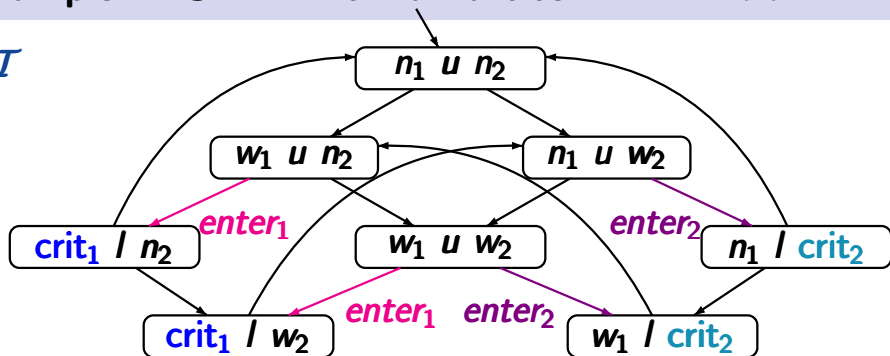
LT property  $E$ : each waiting process eventually enters its critical section

$\mathcal{T} \not\models E$

# Example: MUTEX with fair arbiter

LF2.6-15

$\mathcal{T}$



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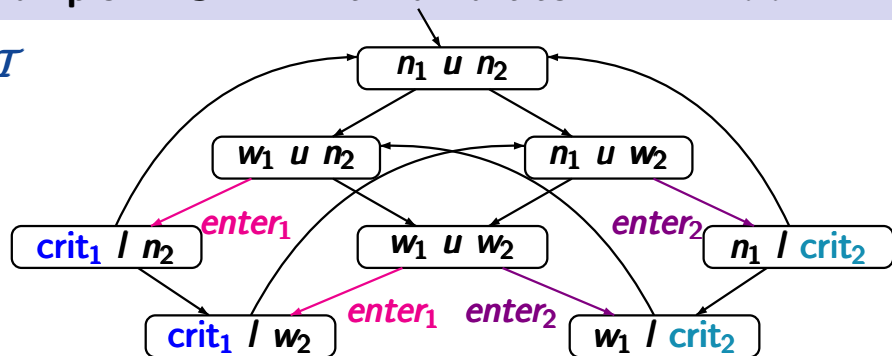
does  $\mathcal{T} \models_{\mathcal{F}} E$  hold ?



# Example: MUTEX with fair arbiter

LF2.6-15

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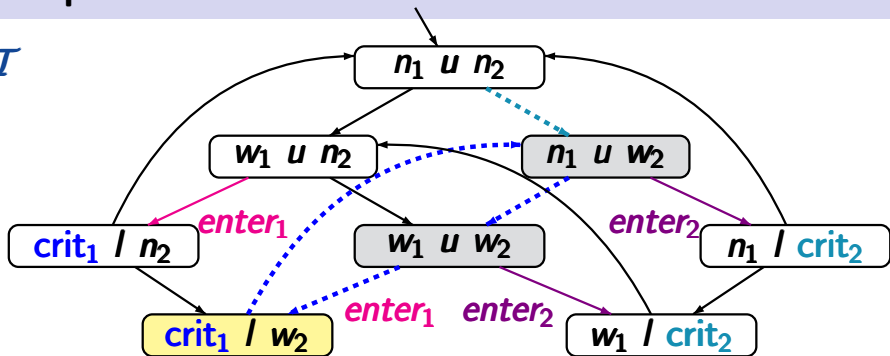
does  $\mathcal{T} \models_{\mathcal{F}} E$  hold ?

answer: **no**

# Example: MUTEX with fair arbiter

LF2.6-15

$\mathcal{T}$



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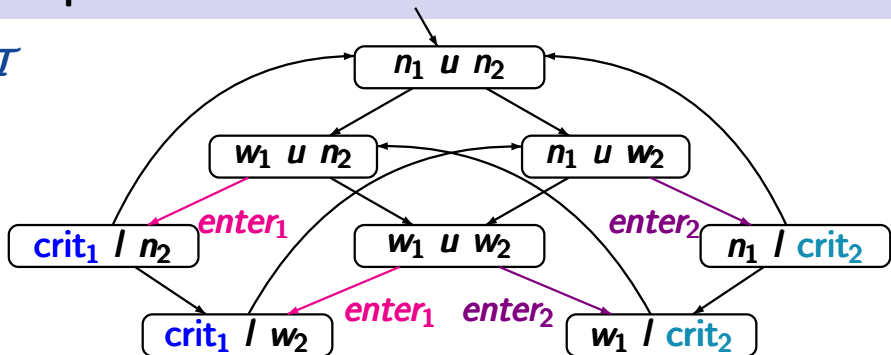
$$\mathcal{T} \not\models_{\mathcal{F}} E$$

as  $enter_2$  is not enabled in  $\langle crit_1, l, w_2 \rangle$

# Example: MUTEX with fair arbiter

LF2.6-16

$\mathcal{T}$



$\mathcal{E}$ : each waiting process eventually enters its crit. section

$\mathcal{F}_{ucond} = ?$

$\mathcal{F}_{strong} = ?$

$\mathcal{F}_{weak} = ?$

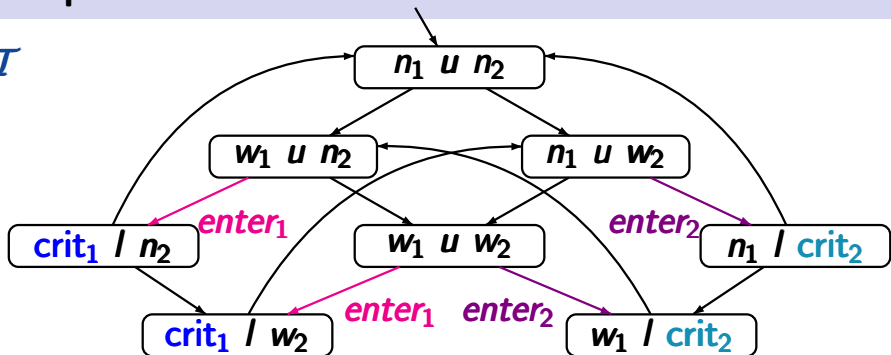
$\mathcal{T} \not\models \mathcal{E}$ ,

but  $\mathcal{T} \models_{\mathcal{F}} \mathcal{E}$

# Example: MUTEX with fair arbiter

LF2.6-16

$\mathcal{T}$



$E$ : each waiting process eventually enters its crit. section

$$\mathcal{F}_{\text{ucond}} = \emptyset$$

$$\mathcal{F}_{\text{strong}} = \{ \{ \text{enter}_1 \}, \{ \text{enter}_2 \} \}$$

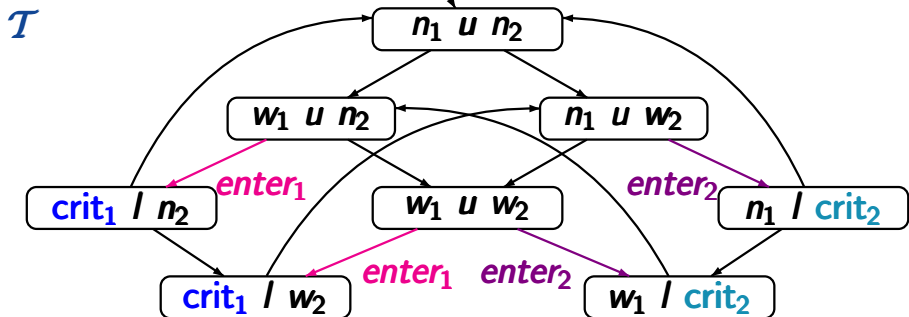
$$\mathcal{F}_{\text{weak}} = \emptyset$$

$$\mathcal{T} \not\models E,$$

$$\text{but } \mathcal{T} \models_{\mathcal{F}} E$$

# Example: MUTEX with fair arbiter

LF2.6-16



$E$ : each waiting process eventually enters its crit. section

$D$ : each process enters its critical section infinitely often

$$\mathcal{F}_{ucond} = \emptyset$$

$$\mathcal{F}_{strong} = \{ \{enter_1\}, \{enter_2\} \}$$

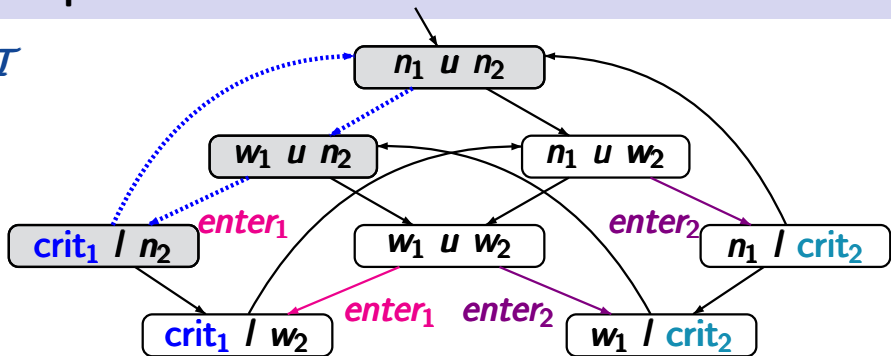
$$\mathcal{F}_{weak} = \emptyset$$

$$\begin{array}{l} \mathcal{T} \models_{\mathcal{F}} E, \\ \mathcal{T} \not\models_{\mathcal{F}} D \end{array}$$

# Example: MUTEX with fair arbiter

LF2.6-16

$\mathcal{T}$



$E$ : each waiting process eventually enters its crit. section

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$$\mathcal{F}_{ucond} = \emptyset$$

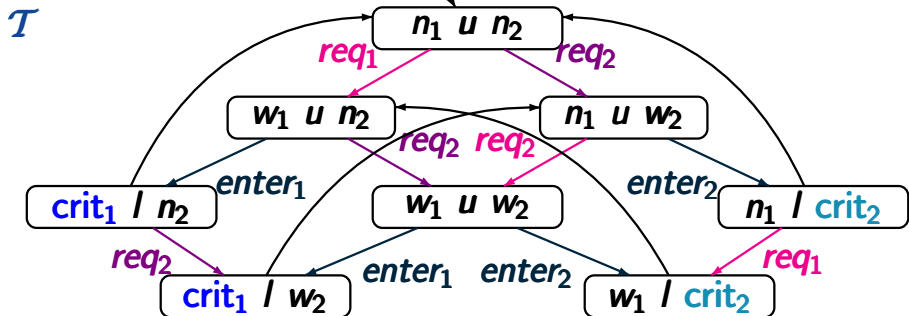
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# Example: MUTEX with fair arbiter

LF2.6-16



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$$\mathcal{F}_{ucond} = \emptyset$$

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$$\mathcal{F}_{weak} = \{ \{req_1\}, \{req_2\} \}$$

$\mathcal{T} \models_{\mathcal{F}} E,$
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For asynchronous systems:

parallelism = interleaving + fairness

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- strong fairness for the
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  - \* resolution of competitions

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- weak fairness for the nondeterminism obtained from the interleaving of independent actions

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rule of thumb:

- strong fairness for the
  - \* choice between dependent actions
  - \* resolution of competitions
- weak fairness for the nondeterminism obtained from the interleaving of independent actions
- unconditional fairness: only of theoretical interest

parallelism = interleaving + fairness

## Process fairness and other fairness conditions

- can compensate **information loss** due to interleaving  
or rule out other **unrealistic pathological cases**
- can be **requirements for a scheduler**  
or **requirements for environment**
- can be **verifiable system properties**

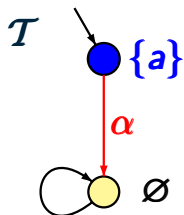
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**liveness properties:** fairness can be **essential**

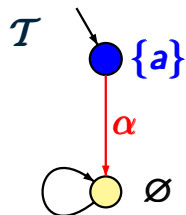
**safety properties:** fairness is **irrelevant**



fairness assumption  $\mathcal{F}$ :  
 unconditional fairness  
 for action set  $\{\alpha\}$

does  $\mathcal{T} \models_{\mathcal{F}}$  “infinitely often  $a$ ” hold ?

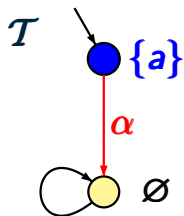




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*answer:* **yes** as there is no fair path

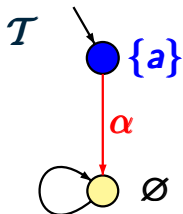


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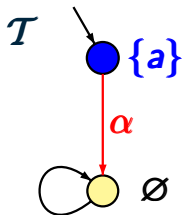
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**Realizability** requires that each initial finite path fragment can be extended to a  $\mathcal{F}$ -fair path



fairness assumption  $\mathcal{F}$ :  
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↑  
*not* realizable

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Fairness assumption  $\mathcal{F}$  is said to be **realizable** for a transition system  $\mathcal{T}$  if for each reachable state  $s$  in  $\mathcal{T}$  there exists a  $\mathcal{F}$ -fair path starting in  $s$



fairness assumption  $\mathcal{F} = (\mathcal{F}_{ucond}, \mathcal{F}_{strong}, \mathcal{F}_{weak})$  for TS  $\mathcal{T}$

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can always be guaranteed by a scheduler, i.e.,  
an instance that resolves the nondeterminism in  $\mathcal{T}$



Realizable fairness assumptions are irrelevant  
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If  $\mathcal{F}$  is a **realizable** fairness assumption for TS  $\mathcal{T}$   
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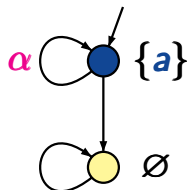
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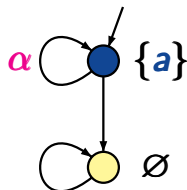
$\mathcal{F}$ : unconditional fairness for  $\{\alpha\}$

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... wrong for non-realizable fairness assumptions



$\mathcal{F}$ : unconditional fairness for  $\{\alpha\}$

$E$  = invariant “always  $a$ ”

$\mathcal{T} \not\models E$ , but  $\mathcal{T} \models_{\mathcal{F}} E$