# Data Mining Cluster Analysis: Basic Concepts and Algorithms

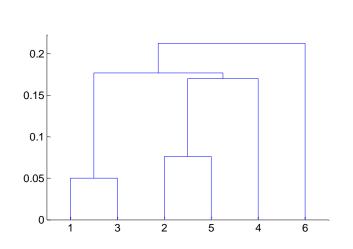
Lecture Notes for Chapter 7

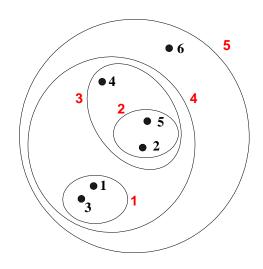
Introduction to Data Mining, 2<sup>nd</sup> Edition by

Tan, Steinbach, Karpatne, Kumar

# **Hierarchical Clustering**

- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
  - A tree like diagram that records the sequences of merges or splits





# Strengths of Hierarchical Clustering

- Do not have to assume any particular number of clusters
  - Any desired number of clusters can be obtained by 'cutting' the dendrogram at the proper level
- They may correspond to meaningful taxonomies
  - Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ...)

# **Hierarchical Clustering**

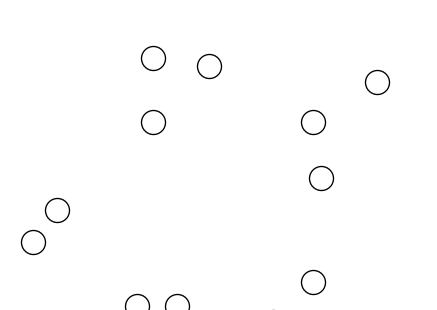
- Two main types of hierarchical clustering
  - Agglomerative:
    - Start with the points as individual clusters
    - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
  - Divisive:
    - Start with one, all-inclusive cluster
    - At each step, split a cluster until each cluster contains an individual point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
  - Merge or split one cluster at a time

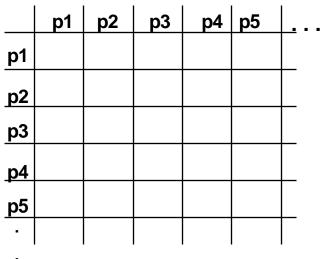
# **Agglomerative Clustering Algorithm**

- Most popular hierarchical clustering technique
- Basic algorithm is straightforward
  - 1. Compute the proximity matrix
  - Let each data point be a cluster
  - 3. Repeat
  - 4. Merge the two closest clusters
  - 5. Update the proximity matrix
  - **6. Until** only a single cluster remains
- Key operation is the computation of the proximity of two clusters
  - Different approaches to defining the distance between clusters distinguish the different algorithms

# **Starting Situation**

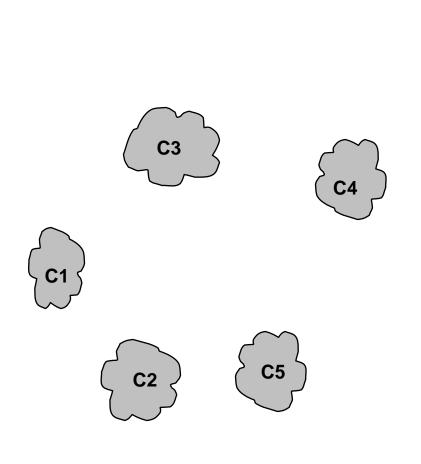
Start with clusters of individual points and a proximity matrix





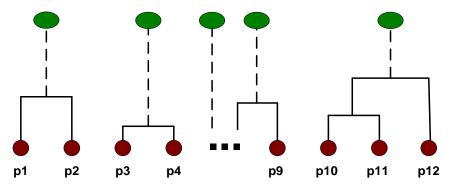
# **Intermediate Situation**

After some merging steps, we have some clusters



	<b>C</b> 1	C2	<b>C</b> 3	<b>C</b> 4	<b>C</b> 5
<u>C1</u>					
C2					
<b>C</b> 3					
<u>C4</u>					
<b>C</b> 5					

**Proximity Matrix** 



# **Intermediate Situation**

We want to merge the two closest clusters (C2 and C5) and

C2

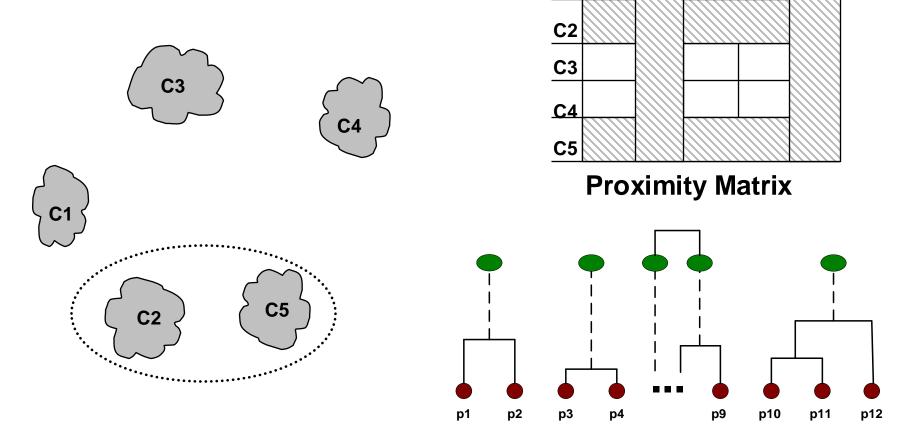
C1

**C**3

**C5** 

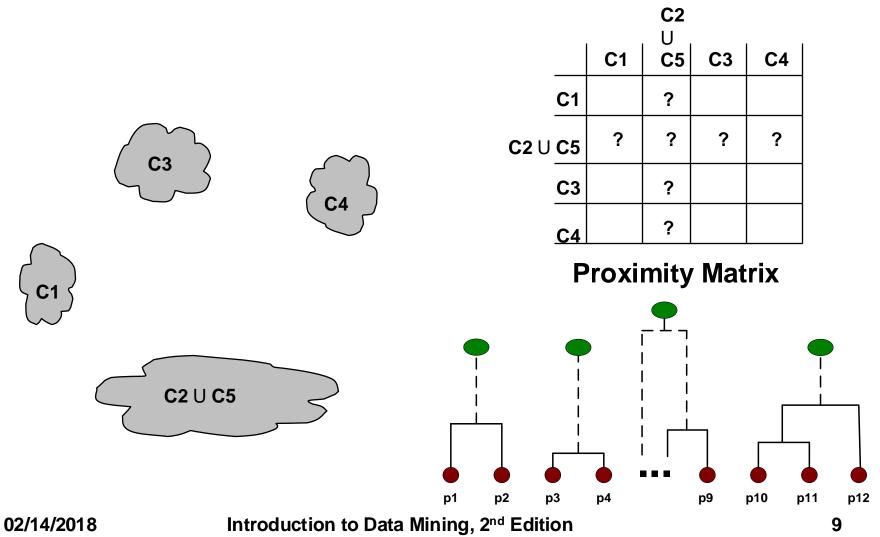
C4

update the proximity matrix.

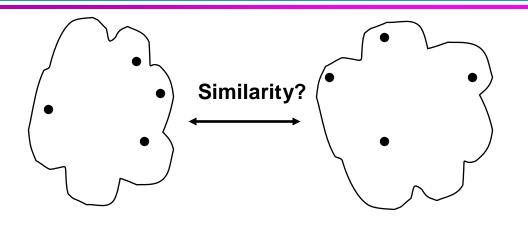


# **After Merging**

The question is "How do we update the proximity matrix?"

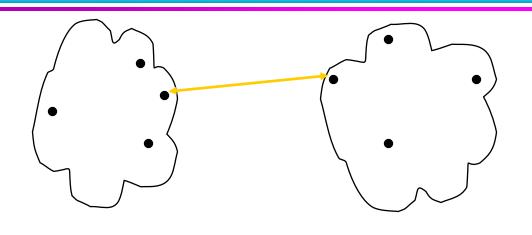


# **How to Define Inter-Cluster Distance**



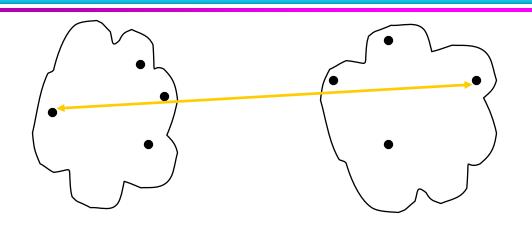
	<b>p1</b>	<b>p2</b>	р3	p4	<b>p</b> 5	<u> </u>
<b>p1</b>						
<b>p2</b>						
рЗ						
<b>p4</b>						
р5						

- MIN
- □ MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error



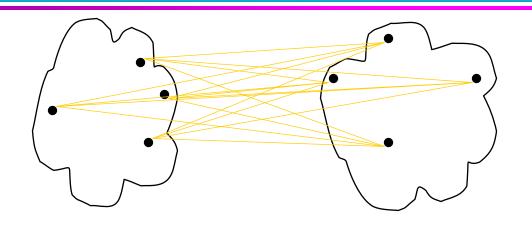
	<b>p</b> 1	<b>p2</b>	рЗ	p4	<b>p</b> 5	<u> </u>
<b>p</b> 1						
<b>p2</b>						
р3						
<u>p4</u>						
р5						
_						

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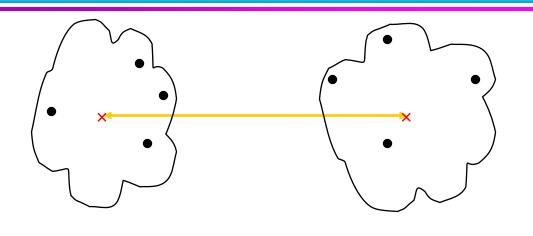
	<b>p</b> 1	<b>p2</b>	р3	p4	<b>p</b> 5	<u> </u>
<b>p1</b>						
<b>p2</b>						
рЗ						
<b>p4</b>						
р5						

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	<b>p</b> 1	<b>p2</b>	р3	p4	<b>p</b> 5	<u> </u>
<b>p1</b>						
<b>p2</b>						
рЗ						
<b>p4</b>						
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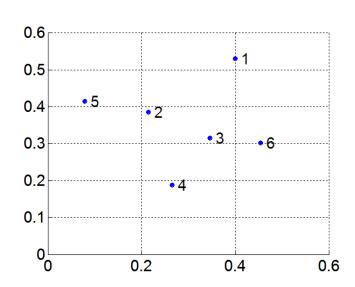
	<b>p</b> 1	p2	рЗ	p4	<b>p5</b>	<u> </u>
р1						
p2						
рЗ						
<b>p</b> 4						
р5						

- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

# MIN or Single Link

- Proximity of two clusters is based on the two closest points in the different clusters
  - Determined by one pair of points, i.e., by one link in the proximity graph

# Example:



### **Distance Matrix:**

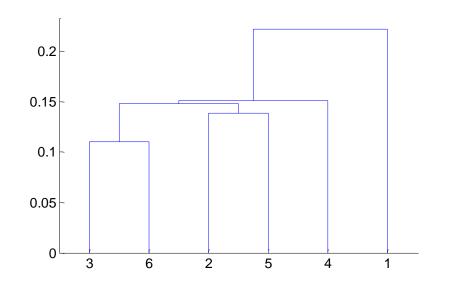
	p1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00

# **Hierarchical Clustering: MIN**

# **3 Nested Clusters**

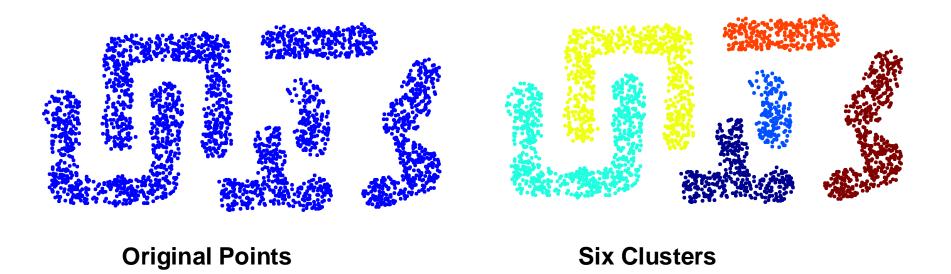
### **Distance Matrix:**

	p1	p2	p3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00



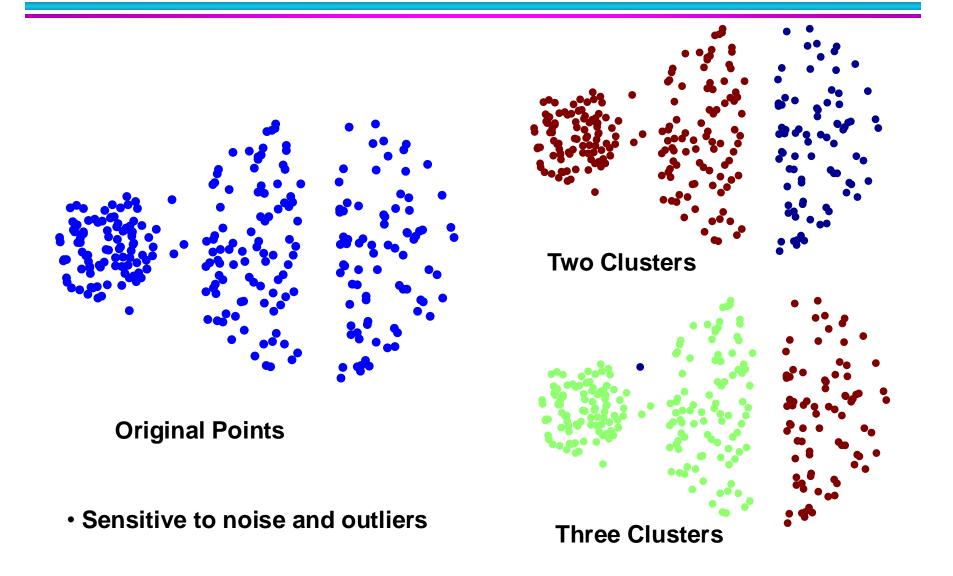
Dendrogram

# **Strength of MIN**



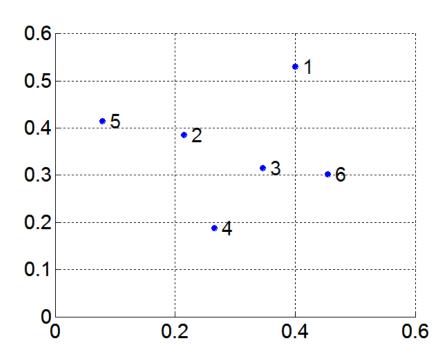
Can handle non-elliptical shapes

# **Limitations of MIN**



# **MAX or Complete Linkage**

- Proximity of two clusters is based on the two most distant points in the different clusters
  - Determined by all pairs of points in the two clusters



### **Distance Matrix:**

	p1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00

# **Hierarchical Clustering: MAX**

### Distance Matrix:

p3

0.22

p4

 $p_5$ 

p6

0.23

p2

p1

0.25

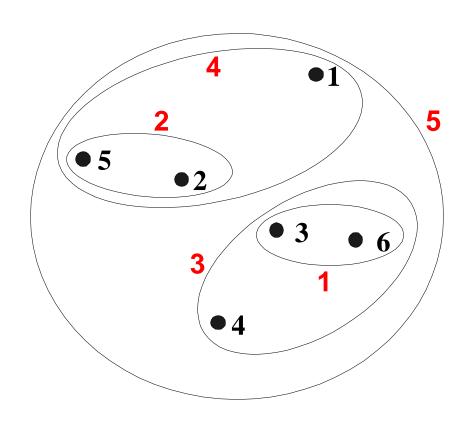
0.2

0.15

0.1

0.05

3



	p2	0.24	0.00	0.15	0.20	0.14	0.25
	p3	0.22	0.15	0.00	0.15	0.28	0.11
	p4	0.37	0.20	0.15	0.00	0.29	0.22
	p5	0.34	0.14	0.28	0.29	0.00	0.39
	p6	0.23	0.25	0.11	0.22	0.39	0.00
	0.4						
(	0.35						
	0.3						

**Nested Clusters** 

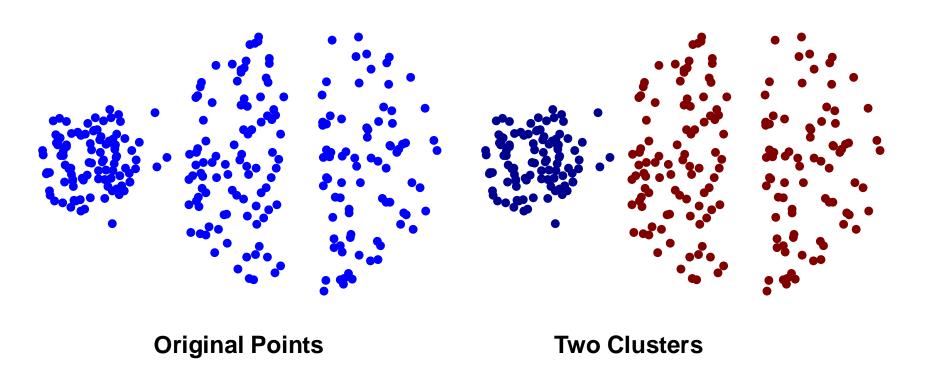
**Dendrogram** 

6

5

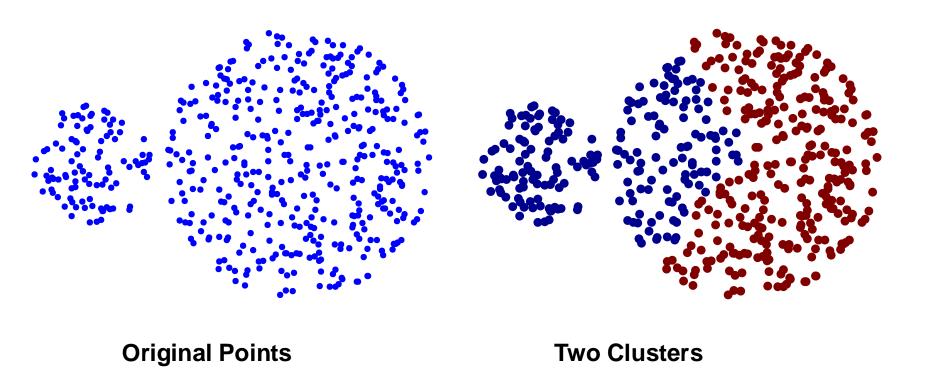
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# **Strength of MAX**



Less susceptible to noise and outliers

# **Limitations of MAX**



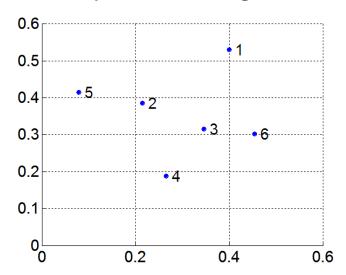
- Tends to break large clusters
- Biased towards globular clusters

# **Group Average**

Proximity of two clusters is the average of pairwise proximity between points in the two clusters.

$$\begin{aligned} & \sum_{p_i \in Cluster_i} proximity(p_i, p_j) \\ proximity(Cluster_i, Cluster_j) &= \frac{p_i \in Cluster_i}{p_j \in Cluster_i} \\ & | Cluster_i | \times | Cluster_i | \end{aligned}$$

 Need to use average connectivity for scalability since total proximity favors large clusters

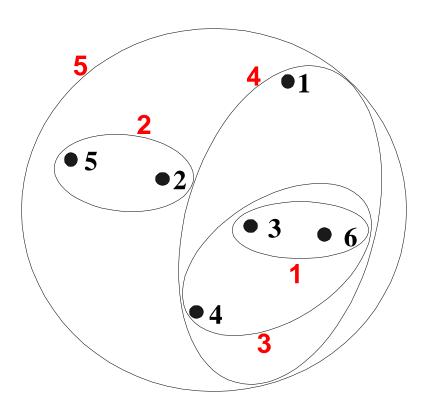


### **Distance Matrix:**

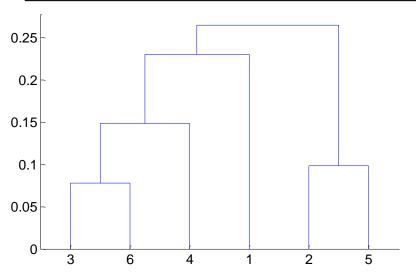
	p1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
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p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00

# **Hierarchical Clustering: Group Average**

### **Distance Matrix:**



	p1	p2	р3	p4	p5	p6
p1	0.00	0.24	0.22	0.37	0.34	0.23
p2	0.24	0.00	0.15	0.20	0.14	0.25
р3	0.22	0.15	0.00	0.15	0.28	0.11
p4	0.37	0.20	0.15	0.00	0.29	0.22
p5	0.34	0.14	0.28	0.29	0.00	0.39
p6	0.23	0.25	0.11	0.22	0.39	0.00



**Nested Clusters** 

**Dendrogram** 

# **Hierarchical Clustering: Group Average**

Compromise between Single and Complete Link

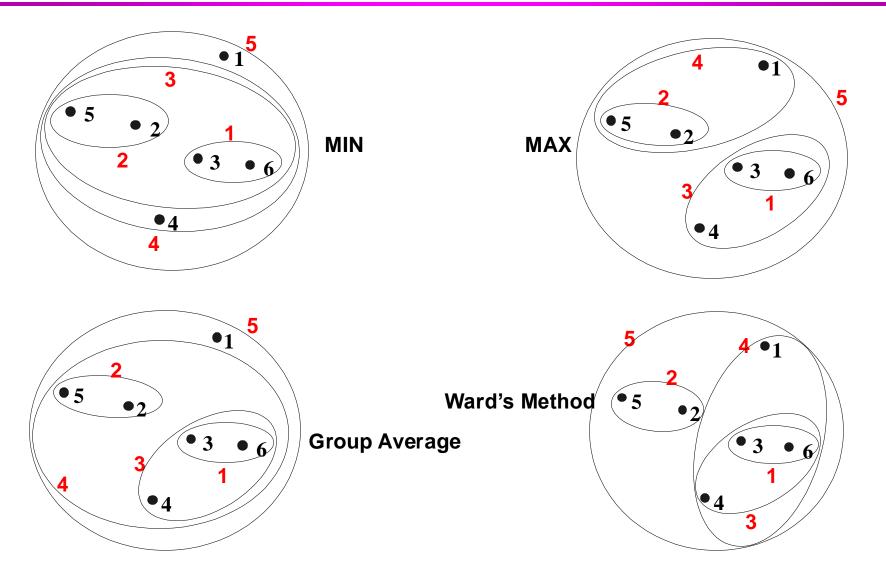
- Strengths
  - Less susceptible to noise and outliers

- Limitations
  - Biased towards globular clusters

# **Cluster Similarity: Ward's Method**

- Similarity of two clusters is based on the increase in squared error when two clusters are merged
  - Similar to group average if distance between points is distance squared
- Less susceptible to noise and outliers
- Biased towards globular clusters
- Hierarchical analogue of K-means
  - Can be used to initialize K-means

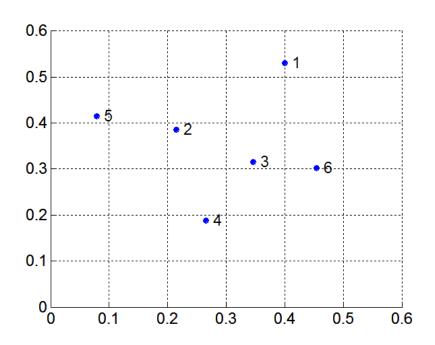
# **Hierarchical Clustering: Comparison**

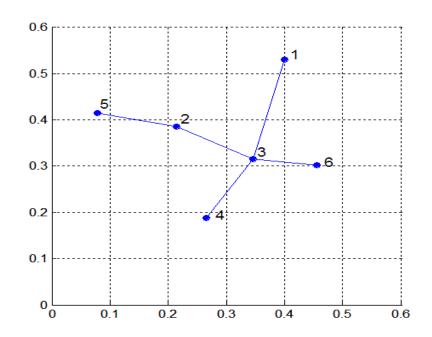


# **MST: Divisive Hierarchical Clustering**

# Build MST (Minimum Spanning Tree)

- Start with a tree that consists of any point
- In successive steps, look for the closest pair of points (p, q) such that one point (p) is in the current tree but the other (q) is not
- Add q to the tree and put an edge between p and q





# **MST: Divisive Hierarchical Clustering**

# Use MST for constructing hierarchy of clusters

### Algorithm 7.5 MST Divisive Hierarchical Clustering Algorithm

- 1: Compute a minimum spanning tree for the proximity graph.
- 2: repeat
- 3: Create a new cluster by breaking the link corresponding to the largest distance (smallest similarity).
- 4: until Only singleton clusters remain

## **Hierarchical Clustering: Time and Space requirements**

- $\square$  O(N<sup>2</sup>) space since it uses the proximity matrix.
  - N is the number of points.
- □ O(N³) time in many cases
  - There are N steps and at each step the size, N<sup>2</sup>, proximity matrix must be updated and searched
  - Complexity can be reduced to O(N<sup>2</sup> log(N)) time with some cleverness

# **Hierarchical Clustering: Problems and Limitations**

- Once a decision is made to combine two clusters, it cannot be undone
- No global objective function is directly minimized
- Different schemes have problems with one or more of the following:
  - Sensitivity to noise and outliers
  - Difficulty handling clusters of different sizes and nonglobular shapes
  - Breaking large clusters